# **Estimating Growth at Risk with Skewed Stochastic Volatility Models**

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# **1. MOTIVATION**

Adrian et al. (2019) analyze the forecasting density of US GDP growth ( $gdp_{t+1}$ ) based on current financial conditions (*nfci<sub>t</sub>*) using a semi-parametric approach.

### **Findings**:

- (1) Lower quantiles of the conditional forecast distribution vary a lot over over time while the upper quantiles remain relatively stable.
- (2) A deterioration of national financial conditions coincides with increases in the interquartile range and decreases the mean.
- (3) Distributions are more symmetric in normal times and become left skewed in recessionary periods
- Drawbacks of the semi-paramteric approach:
  - Time variation of the distribution is not parametrically characterized
  - Does not allow for parameter inference
- Use a fully parametric model to analyze the evolution of the conditional forecast distributions and conduct statistical inference on the estimated parameters.

## 2. SKEWED STOCHASTIC VOLATILITY MODEL

# **4. ESTIMATION RESULTS**

The model is estimated on the same data set as used by Adrian et al. (2019) with four Markov chains ran in parallel on the HPC-Cluster at the Freie Universität.

#### **4.1 Static Parameters**

<b>Model Parameter</b>	Mean	SD	q05	q95
$\gamma_0$	2.217	0.335	1.69	2.799
$\gamma$ 1	-0.695	0.236	-1.125	-0.351
$\delta_{1,0}$	1.295	0.385	0.784	2.06
$\delta_{1,1}$	0.292	0.198	0.106	0.556
$\delta_{1,2}$	0.388	0.139	0.197	0.647
$\delta_{2,0}$	0.401	0.305	-0.904	0.649
$\delta_{2,1}$	-0.429	0.226	-0.81	-0.038
$\sigma_{ u_1}$	0.451	0.119	0.298	0.688
$\sigma_{ u_2}$	0.533	0.182	0.319	0.877

 $\blacktriangleright$  *nfci<sub>t</sub>* has a negative impact on the mean and skewness and a positive impact on the

The Skewed Stochastic Volatility Model (SSV) is a non-linear, non-Gaussian state space model with measurement equation

$$gdp_{t+1} = \gamma_0 + \gamma_1 nfci_t + \varepsilon_{t+1}$$
 with  $\varepsilon_t \sim skew \mathcal{N}(0, \sigma_t, \alpha_t)$ 

and state equations

$$\ln(\sigma_{t}) = \delta_{1,0} + \delta_{1,1} nfci_{t} + \delta_{1,2} \ln(\sigma_{t-1}) + \nu_{1,t}$$
  
$$\alpha_{t} = \delta_{2,0} + \delta_{2,1} nfci_{t} + \delta_{2,2} \alpha_{t-1} + \nu_{2,t}.$$

- $\triangleright$   $\nu_{1,t}$  and  $\nu_{2,t}$  are assumed to be uncorrelated Gaussian White Noise innovations
- Errors in the measurement equation are distributed according to the skewed Normal distribution of Azzalini (2013).

0.1

Similar to the normal distribution it has has parameters for **location** ( $\mu$ ) and **scale** ( $\sigma$ ) plus an additional parameter that determines its **shape** ( $\alpha$ ):

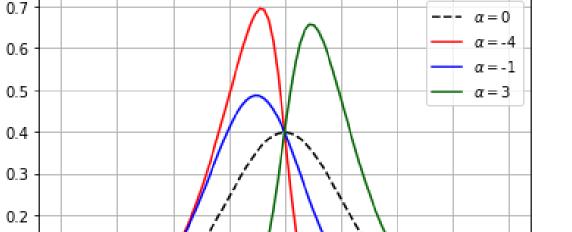
skew 
$$\mathcal{N}(\mathbf{y}|\mu,\sigma,\alpha) = \frac{2}{\sqrt{(2\pi)}\sigma} e^{-\frac{(\mathbf{y}-\mu)^2}{2\sigma^2}} \int_{-\infty}^{\alpha\frac{\mathbf{y}-\mu}{\sigma}} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$$

 $\rightarrow$  *nfci<sub>t</sub>* can affect all three moments.

 $\longrightarrow$  Kurtosis evolves endogenously.

# **3. ESTIMATION METHOD**

Based on the work of Kim et al. (1998), the skewed stochastic volatility models is estimated using a Particle Metropolis Hastings algorithm:



Density of the Skewed Normal Distribution ( $\mu = 0, \sigma^2 = 1$ )

0.0 Figure: Skew-Normal Density

 $---\alpha = 0$ 

- volatility.
- Estimated parameter values for the effect of financial conditions on the variance and skewness of the conditional distributions are significant based on 90% credible sets.

#### **Posteriors Densities:**

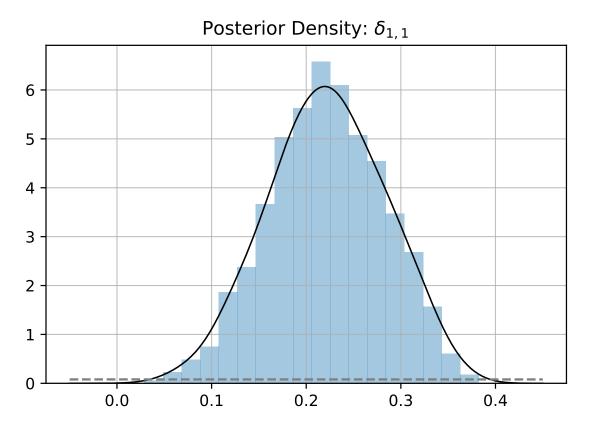


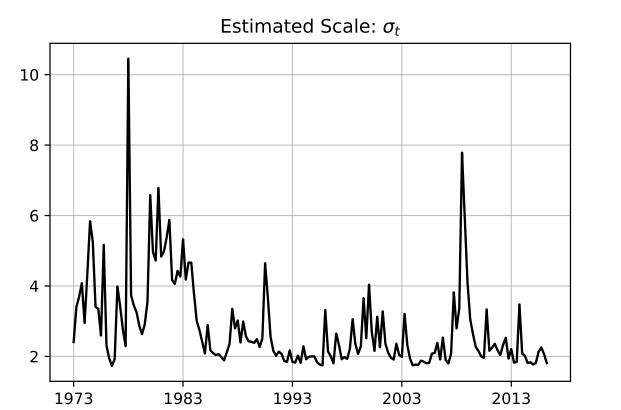
Figure: Impact of *nfci<sub>t</sub>* on the scale

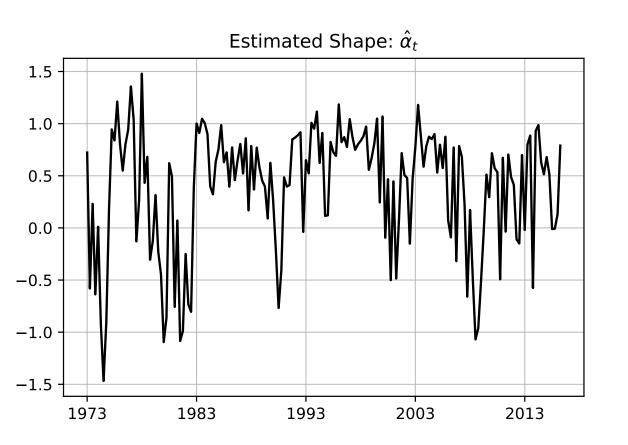
#### 2.00 1.75 1.50 1.25 1.00 0.75 0.50 0.25 0.00 -1.25 -1.00 -0.75 -0.50 -0.25 0.000.25 0.50

Posterior Density:  $\delta_{2,1}$ 

Figure: Impact of *nfci<sub>t</sub>* on the shape

### **4.2 Time-varying Parameters**





Static Model Parameters ( $\theta = (\delta_0, \delta_1, \gamma_{1,0}, \gamma_{1,1}, \gamma_{1,2}, \gamma_{2,0}, \gamma_{2,1}, \gamma_{2,2}, \sigma_{\nu,1}, \sigma_{\nu,2})$ ) are estimated using a Metropolis Hastings sampler with stationary distribution

$$p(\theta|y_{1:T}, s_{1:T}) = \frac{p(y_{1:T}|s_{1:T}, \theta)p(s_{1:T}|\theta)p(\theta)}{p(y_{1:T})}$$

**Time varying model parameters** ( $s_t = (\ln \sigma_t, \alpha_t)$ ) are estimated using the tempered particle filter from Herbst and Schorfheide (2019) to approximate the filtering distribution

$$p(s_t|y_{1:t}) = \frac{p(y_t|s_t)p(s_t|y_{1:t-1})}{\int p(y_t|s_t)p(s_t|y_{1:t-1})ds_t}$$

using sequential importance sampling.

#### **3.1 Tempered Particle Filter**

- The tempered particle filter uses annealed importance sampling to obtain a better proposal density using a sequence of  $N_{\phi}$  bridge distributions.
- ▶ Building on the adaptive tempering schedule of Herbst and Schorfheide (2019), I use a tempering scheme that jointly tempers the variance and tilts the density towards the actual level while targeting a predetermined inefficiecy ratio  $r^*$ :

$$p_n(y_t|s_{t,i}) = skew \mathcal{N}(y_t|\mu_t, \sigma_{t,i}/\phi_n, \phi_n\alpha_{t,i})$$
 with  $0 < \phi_n < 1$  and  $\lim_{n \to N_\phi} \phi_n = 1$ .

This gives the unnormalized weights at the n<sup>th</sup> tempering step as

$$\tilde{W}_{t,i}(\phi_n) = \left(\frac{\phi_n}{\phi_{n-1}}\right)^2 \exp\left(\frac{-(\phi_n - \phi_{n-1})(y_t - \mu_t)}{2\sigma_{t,i}}\right)^2 \tilde{\Lambda}_{t,i}(\phi_n)$$

with

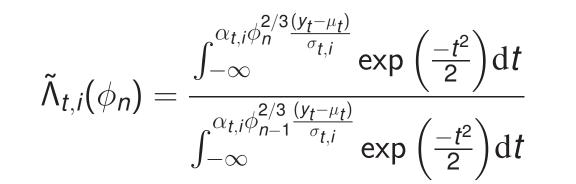
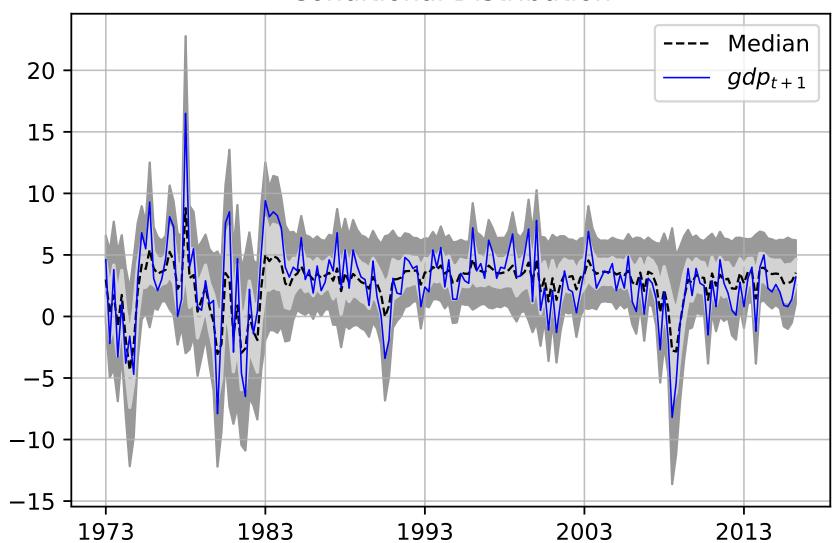


Figure: Volatility over time

Figure: Skewness over time

- Volatility and downside risk increase in the 1980s and during the Great Recession
- lncreases in volatility occur with an increase in downside risks ( $\rho[\alpha_t, \sigma_t^2] = -0.41$ )
- $\blacktriangleright$  The estimated state of  $\alpha_t$  even exhibits positive skewness in times of moderation similar to the findings of delle Monache et al. (2021)

#### **4.3 Conditional Forecast Densities**



#### **Conditional Distribution**

#### Figure: Estimated forecasting densities

- Lower and upper 5% and 25% percent quantiles of the one-period ahead forecasting density
- While the upper quantiles remain relatively stable, the lower quantiles vary strongly over
- Additionally tempering the symmetry of the distribution reduces the number of tempering steps  $N_{\phi}$  by about 25%.

#### 3.2 Tuning

- The Tempered Particle Filter is tuned using M = 40000 particles with a targeted Inefficiency ratio  $r^* = 1.2$  and 2 mutation steps in each tempering iteration.
- $\blacktriangleright$  The model is estimated based on N = 20000 draws of the Particle Metropolis Hastings Algorithm using a standard Random Walk proposal with an estimate of the proposal variance  $Var(\theta) = \hat{\Omega}$  based on a pre-run.
- Mixture of uninformative and informative priors on the static parameters.

time indicating increased downside risk to GDP growth in times of financial distress

### 5. CONCLUSION

- I propose a Skewed Stochastic Volatility model to analyze Growth at Risk and conduct statistical inference on the estimated parameters
- ► The model is estimated using Bayesian Methods. The tempering schedule of the tempered particle filter is adapted to asymmetric distributions.
- The estimated parameter values for the effect of financial conditions on the variance and skewness of the conditional distributions are significant and in line with other recent studies.

#### References

[1] Adrian, T., N. Boyarchenko, and D. Giannone (2019). Vulnerable growth. American Economic Review 109 (4), 1263-89. [3] Herbst, E. and F. Schorfheide (2019). Tempered particle filtering. Journal of Econometrics 210 (1), 26-44. [2] delle Monache, D., A. de Polis, and I. Petrella (2021). Modeling and forecasting macroeconomic downside risk. Working [4] Kim, S., N. Shephard, and S. Chib (1998). Stochastic volatility: Likelihood inference and comparison with arch models. Papers 1324, Banca d'Italia The Review of Economic Studies 65 (3), 361-393



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