## Appendix A The adiabatic approximation

The essence of the adiabatic approximation is as follows. Following [118] we suppose that we a have system of linear differential equations:

$$\frac{d}{dt}\rho(t) = \hat{Z}(t)\rho(t), \qquad (A.1)$$

where  $\rho(t)$  is the n-dimensional vector, while  $\hat{Z}(t)$  is the n by n matrix. We choose initial conditions:  $\rho(t)|_{t_0} = \rho_0$ . If eigenvectors  $a_n(t)$  and eigenfrequencies  $\omega_n(t)$  of the matrix  $\hat{Z}(t)$  vary slowly with t:

$$\frac{d}{dt}\omega_n(t) \ll (\omega_n(t))^2, \ \frac{d}{dt}|a_n(t)| \ll \omega_n(t)|a_n(t)|, \tag{A.2}$$

then the adiabatic approximation of the solution of the set of linear equations Eq. [A.1] may be represented in the form:

$$\rho_n(t) = a_n(t) \exp(\int_{t_0}^t \omega_n(t') dt').$$
(A.3)

Indeed, let us substitute Eq. [A.3] in Eq. [A.1] and get

$$\dot{a}_n(t)\exp(\int_{t_0}^t \omega_n(t')dt') + \omega_n(t)a_n(t)\exp(\int_{t_0}^t \omega_n(t')dt') = \hat{Z}(t)a_n\exp(\int_{t_0}^t \omega_n(t')dt').$$
(A.4)

Under the slowness condition Eq. [A.2], the first term on the left-hand side of Eq. [A.4] is small compared to the second one and may by omitted. Then Eq. [A.4] only keeps the terms yielding the identity that determines the eigenfrequency  $\omega_n$ .