Introduction

The dance of the honeybee *Apis mellifera* had been described several times by attentive naturalists dating back to Aristotle, by the time Karl von Frisch dedicated himself to elucidating its enormous complexity and to finally uncovering the meaning of several different components of what he termed the dance language (von Frisch 1965). Ever since then, an unremittingly growing community of scientists has described more and more astounding abilities of this animal. Studies of honeybee communication, foraging and social behaviour as well as their co-evolution with flowering plants have not lost their topicality, but rather provide a basis for combined studies of evolution, ecology, behaviour and neurobiology – to name just those fields that are addressed in my dissertation.

Entomophilous flowers have also been studied extensively since Christian Konrad Sprengel first published his "Uncovered Mystery of Nature in the Construction and Fertilisation of Blossoms" in 1793. He clarified that the two most prominent flower properties – colour and scent – are not presented to please humans, but to attract a great variety of pollinators. Many additional aspects of pollination have since been discovered (Faegri & van der Pijl 1979, Jones and Little 1983, Paulus 1988, Waser and Ollerton 2006). The mutual influences in the plant-pollinator system also roused my interest, especially with regard to floral colours and bee pollinators.

The honeybee has been found exceedingly expedient to the study of many aspects of learning and memory (Menzel and Erber 1978, Gould and Towne 1987, for reviews see: Gould 1984, Menzel 1985, 1990, 2003). Questions that I approached in my dissertation deal with their learning abilities during foraging, i.e. learning about floral colours, reward properties and reliabilities. It is known for a long time that honeybees are able to perceive colours, to discriminate different colours and associate them with a reward (von Frisch 1914, Kühn 1923, Daumer 1956, Menzel 1967). They belong to the group of Apoidea, which are the most important pollinators. They also have the best-studied receiver colour vision system of all insects and thus fulfil an indispensable requirement for an adequate description of colour signals (Menzel and Backhaus 1991, Peitsch *et al.* 1992). Bees differ strongly from humans in their colour perception, because the wavelength range to which they are sensitive is shifted towards the shorter wavelengths. Similarly to humans, they also have three photoreceptor types, but their maximum sensitivities are in the ultraviolet, blue and green parts of the visual

spectrum. Therefore, one has to design behavioural experiments to examine the bees' colour perception and its influence on foraging and communication behaviour or one has to use adequate models of bee colours vision to quantify perceptual similarities of colours (Vorobyev *et al.* 2001). I applied both approaches during my studies.

During foraging, bees develop a reward expectation, which is predicted through the related signal (Menzel 1985). Associations between different colour and reward properties can be learned and compared in terms of efficiency and profitability, which usually leads to a temporary preference for one signal. This phenomenon applied to the conditions in the bee's natural environment is called floral constancy (von Frisch 1927, Grant 1950, Goulson 1999). But foraging decisions are based on many additional aspects, e.g. distance to the food source, abundance of single sources, competition and requirements of the colony (Heinrich *et al.* 1977, Hill *et al.* 1997, for a review see: Chittka *et al.* 1999). Profitable food sources are communicated to nestmates inside the hive via the dance behaviour (von Frisch 1965, Waddington 1982, 2001, Seeley 1995, 2000), which shows that bees are able to estimate, among other things, the flow rate of the reward as well as the time invested by the forager to obtain the reward (Varjú and Núñez 1991). Fülöp and Menzel (2000) showed that honeybees show risk-indifferent foraging behaviour, but so far it could not be shown that this behavioural trait affects dance communication.

Following up on these ideas, I addressed the question of whether honeybees are able to estimate reward reliability independently of energy gain or loss during their foraging bout, and whether they are able to adapt their dance behaviour according to this evaluation of perceived profitability (Chapter I). This experimental work was performed by means of a flight arena containing artificial coloured targets whose actual and perceived profitabilities could be manipulated under controlled conditions. The advantage of these laboratory conditions compared to field conditions is that the motivational status of the animal can be held constant and sensory cues can be substantially reduced to focus on only one aspect of profitability. The results would play a role in the comprehension of bee behaviour, especially with respect to foraging strategies, dance communication and cognitive abilities of honeybees. On the other hand, I was interested in the effects that floral constancy may have on flower colour distribution in the natural environment. Flowering plants require their pollinators' floral constancy to obtain efficient pollination. It is believed that during the process of coevolution, plants adapted their floral colouration to the visual properties of the pollinators, while many pollinators' colour vision has indeed evolved such that they are able to discriminate flowers well (Chittka et al. 1994, Vorobyev and Menzel 1999). Bees, moreover,

are able to perceive many additional colours besides those found in floral displays (Vorobyev and Menzel 1999). The extent to which pollinators influenced flower colour evolution, is still a controversial discussion. Conclusions from different authors range from opinions that pollinators' preferences are too broad to effectuate floral characteristics (Waser et al. 1996, Chittka et al. 1999) to likelihoods for the adaptive divergence of floral traits through pollinator-mediated selection (Schemske and Bradshaw 1999, Gumbert and Kunze 2001, Gigord et al. 2002). In Chapter II and III, I present my contribution to the ongoing discussion. I looked at the distribution of flower colours and reward properties in simultaneously flowering species. I investigate whether a non-random distribution of colours in highly rewarding plant species in the natural environment might be the reason for the formation of innate colour preferences and/or for differences in learning speed of different colours in honeybees and bumblebees (Menzel 1967, 1968, 1969, Giurfa et al. 1995, Gumbert 2000). I also compared plant species that display similar or indistinguishable colours on the basis of their reward properties to find out whether generalisation of colours during foraging is a rewarding and reliable foraging strategy. Special emphasis was placed on the colour analysis as perceived by honeybees by using the Receptor Noise Limited Model of honeybee colour vision (Vorobyev et al. 2001). Additionally, I investigated influences of further floral properties, e.g. floral abundance, display size and functional flower shape, on the foraging decisions of bee pollinators to achieve an integrated picture of the complex interactions in undisturbed plant-pollinator communities.

Efficient pollination, as required by entomophilous plants, is facilitated, when flowers are not only reliable, but also easily detected by the pollinator. Most studies thus far analysed the relationship between floral display size and detection or visitation rates (individual level: Robertson and Macnair 1995, Giurfa *et al.* 1996, Stout 2000, Spaethe *et al.* 2001; species level: Biernaskie and Cartar 2004, Grindeland *et al.* 2005, Stang *et al.* 2006). But the enlargement of the single floral display during co-evolution of plants and pollinators is not the only possibility. Alternatively, some species evolved inflorescences that consist of several single flowers, thereby also enlarging the coloured area. As a result, they may be more conspicuous to an insect. However, it is not known how spatial patterning of flower and background colours in complex plant displays affects the insect's perception of targets.

The visual system of the honeybee consists of two different parts coding chromatic and achromatic aspects of visual information (Brandt and Vorobyev 1996, Giurfa *et al.* 1996, 1997, Giurfa and Vorobyev 1998, Hempel de Ibarra *et al.* 2001, 2002, Niggebrügge and Hempel de Ibarra 2003). Chromatic vision is achieved by colour-opponent computation of

receptor signals and is used by honeybees for the detection and discrimination of coloured targets which are close to the bee. Achromatic vision is mediated only by one single receptor type or the summation of receptor responses. The detectability of targets with small angular subtenses depends on the Long wavelength sensitive (L)-receptor contrast between target and background or within the target (Lehrer & Bischoff 1995, Hempel de Ibarra et al. 2001). The proposed processing of L-receptor mediated achromatic information by neurons that have a centre-surround organisation (Hempel de Ibarra et al. 2001) satisfactorily explain the fact that the detectability of targets is enhanced when stimuli have enhanced edges while it is impaired for targets with blurred edges.

I addressed the question of how spatial cues interact with target detection if single-coloured targets are grouped. I aimed to find out whether the detectability of patterns is related to the amount and density of borders, rather than to the area of the target (Chapter IV). The experiment was carried out under laboratory conditions with honeybees and bumblebees that were presented with targets with either an L-receptor contrast to the background or not. The obtained results were then considered when designing measurements of display sizes of flowers presented in Chapter II.

Yet another way, in which plants attract pollinators, is via the sharing of signals with other plants that are successfully visited owing to their profitability – a phenomenon known as flower mimicry of Müllerian type (Dafni 1984, 1986, Roy and Widmer 1999). Müllerian mimicry is mutualistic and involves two or more species with rewarding flowers, which may benefit from sharing a common advertising display. In this case, improper pollen transfer might be avoided by reaching a higher combined flower density (Rathcke 1983, Waser 1983). Müllerian mimicry occurs in contrast to the strategy of diversifying as widely as possible from co-flowering plants in order to ensure correct pollination through bees' floral constancy (Waser 1983). In Chapter V, the adaptiveness of Müllerian similarity between species is demonstrated for the first time by means of two species that belong to families in which flower mimicry had not been suspected before: *Sphaeralcea cordobensis* (Malvaceae) and *Turnera sidoides* ssp. *pinnatifida* (Turneraceae).

The diversified approaches combined in my dissertation range from controlled behavioural experiments to observational studies under natural conditions. I integrated physical characterisations of signal properties into my interpretation of the sensory physiology of the bee pollinators to be able to judge their behavioural impact on the appearance and ecology of plants. In this way, I hope to give the reader a holistic insight into the complexity of the evolution of the plant-pollinator system.

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