#### CHAPTER 2

## BOUNDARY VALUE PROBLEMS FOR SECOND ORDER PARTIAL DIFFEENTIAL EQUATIONS IN THE PLANE WITH FUCHS OPERATOR IN THE MAIN PART

In this chapter continuous solutions in an unbounded angular domain of the Dirichlet and the Neumann problem, an initial problem with given growth at infinity for some classes of partial differential equations of second order with Fuchs operator in the main part are constructed. Thus the varieties of continuous solutions constructed in the first section are used. These problems are regularly investigated here for the first time.

# 2.1 Dirichlet and Neumann problems with given growth at infinity for a model second order partial differential equation in the plane with Fuchs operator in the main part and specified right hand side

Dirichlet problem. Let us consider the Dirichlet problem for equation (1.1). **Problem**  $D_1$ . Let  $\beta \neq \alpha + \gamma$ . It is required to find the solution of the equation

(0.1) from the class  $W_p^2(G)$ , where  $1 , if <math>\lambda < 2$  and p > 1, if

 $\lambda \ge 2$ , satisfying the conditions

$$|V(r,\varphi)| = \mathcal{O}(r^{\lambda}), r \to \infty, \qquad (2.1)$$

$$V(r,0) = b_1 r^{\lambda}, \ V(r,\varphi_1) = b_2 r^{\lambda}, \tag{2.2}$$

where  $b_1, b_2$  are given complex numbers,  $\lambda > 0$  is a real number.

**Solving the problem.** For solving problem  $D_1$  we use the formula (1.17). Then it automatically satisfies (2.1). From the forms of the functions  $(BF)(\varphi)$ ,  $P_{\nu,1}(\varphi) P_{\nu,2}(\varphi), Q_{\nu,1}(\varphi), Q_{\nu,2}(\varphi)$  follow

$$(BF)(0) = 0$$
,  $P_{\nu_1}(0) = 0$ ,  $Q_{\nu_1}(0) = 0$ ,

$$P_{\nu,2}(0) = \begin{cases} 1, & \text{if } \nu \neq 0, \\ 0, & \text{if } \nu = 0, \end{cases} \qquad Q_{\nu,2}(\varphi) = \begin{cases} 1, & \text{if } \nu \geq 0, \\ 0, & \text{if } \nu < 0. \end{cases}$$
(2.3)

From (1.17) in view of (2.3) we have

$$V(r,0) = (c_1 \delta_{\nu,1} + c_2 \delta_{\nu,2}) r^{\lambda},$$

where

re  $\delta_{\nu,1} = \begin{cases} 1, if \ \nu \neq 0, \\ 0, if \ \nu = 0, \end{cases}$   $\delta_{\nu,2} = \begin{cases} 1, if \ \nu \ge 0, \\ 0, if \ \nu < 0. \end{cases}$ 

Therefore from the boundary conditions (2.2) depending on the sign of  $v = \frac{(4\alpha\gamma - \beta^2)\lambda^2 + 2(\beta(\alpha + \gamma) - 4\alpha\gamma)\lambda - (\alpha - \gamma)^2}{q^2}$  follow some algebraic system

of equations for  $c_1$  and  $c_2$ :

1) Let 
$$v = 0$$
. Then  
 $c_2 = b_1$ ,  
 $P_{v,2}(\varphi_1)c_1 + P_{v,1}(\varphi_1)\overline{c_1} = \Delta_1(\varphi_1)$ ,  
where  $\Delta_1(\varphi_1) = b_2 e^{-a\varphi_1} - (BF)(\varphi_1) - b_1 Q_{v,2}(\varphi_1) - \overline{b_1} Q_{v,1}(\varphi_1)$ .

2) Let 
$$v < 0$$
. Then  
 $c_1 = b_1$ ,  
 $Q_{v,2}(\varphi_1)c_2 + Q_{v,1}(\varphi_1)\overline{c_2} = \Delta_2(\varphi_1)$ ,  
where  $\Delta_2(\varphi_1) = b_2 e^{-a\varphi_1} - (BF)(\varphi_1) - b_1 P_{v,2}(\varphi_1) - \overline{b_1} P_{v,1}(\varphi_1)$ .  
3) Let  $v > 0$ . Then  
 $c_1 + c_2 = b_1$ ,  
 $(Q_{v,2}(\varphi_1) - P_{v,2}(\varphi_1))c_2 + (Q_{v,1}(\varphi_1) - P_{v,1}(\varphi_1))\overline{c_2} = \Delta_2(\varphi_1)$ .

Each of these systems has unique solutions in case

1) 
$$v = 0$$
,  $|P_{v,2}(\varphi_1)|^2 \neq |P_{v,1}(\varphi_1)|^2$ ,  
2)  $v < 0$ ,  $|Q_{v,2}(\varphi_1)|^2 \neq |Q_{v,1}(\varphi_1)|^2$ ,  
3)  $v > 0$ ,  $|Q_{v,2}(\varphi_1) - P_{v,2}(\varphi_1)|^2 \neq |Q_{v,1}(\varphi_1) - P_{v,1}(\varphi_1)|^2$ .  
(2.4)

From these conditions the solution are found by the formulas:

1) If 
$$v = 0$$
,  $|P_{v,2}(\varphi_1)|^2 \neq |P_{v,1}(\varphi_1)|^2$ , then  
 $c_2 = b_1, c_1 = \frac{\Delta_1(\varphi_1)\overline{P_{v,2}(\varphi_1)} - \overline{\Delta_1(\varphi_1)}P_{v,1}(\varphi_1)}{|P_{v,2}(\varphi_1)|^2 - |P_{v,1}(\varphi_1)|^2}$ . (2.5)  
2) If  $v < 0$ ,  $|Q_{v,2}(\varphi_1)|^2 \neq |Q_{v,1}(\varphi_1)|^2$ , then  
 $c_1 = b_1, c_2 = \frac{\Delta_2(\varphi_1)\overline{Q_{v,2}(\varphi_1)} - \overline{\Delta_2(\varphi_1)}Q_{v,1}(\varphi_1)}{|Q_{v,2}(\varphi_1)|^2 - |Q_{v,1}(\varphi_1)|^2}$ . (2.6)  
3) If  $v > 0$ ,  $|Q_{v,2}(\varphi_1) - P_{v,2}(\varphi_1)|^2 \neq |Q_{v,1}(\varphi_1) - P_{v,1}(\varphi_1)|^2$ , then  
 $c_1 = \frac{\Delta_2(\varphi_1)(\overline{Q_{v,2}(\varphi_1)} - \overline{P_{v,2}(\varphi_1)}) - \overline{\Delta_2(\varphi_1)}(Q_{v,1}(\varphi_1) - P_{v,1}(\varphi_1))|^2}{|Q_{v,1}(\varphi_1) - \overline{P_{v,1}(\varphi_1)}|^2}$ . (2.7)

$$c_{2} = \frac{2(P_{1})(2\nu_{2}(P_{1}) - \nu_{2}(P_{1}))}{\left|Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1})\right|^{2} - \left|Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1})\right|^{2}},$$
(2.7)

 $c_1 = b_1 - c_2$ .

Hence, the following result holds.

**Theorem 2.1**. When conditions (2.4) are fulfilled, problem  $D_1$  has a unique solution. In this case the unique solution is then given by the formulas (1.17), (2.5)-(2.7).

In case

1) 
$$v = 0$$
,  $|P_{\nu,2}(\varphi_1)|^2 = |P_{\nu,1}(\varphi_1)|^2$ ,  
2)  $v < 0$ ,  $|Q_{\nu,2}(\varphi_1)|^2 = |Q_{\nu,1}(\varphi_1)|^2$ ,  
3)  $v > 0$ ,  $|Q_{\nu,2}(\varphi_1) - P_{\nu,2}(\varphi_1)|^2 = |Q_{\nu,1}(\varphi_1) - P_{\nu,1}(\varphi_1)|^2$ 
(2.8)

for the solvability of the indicated algebraic systems is necessary and sufficient that the following conditions are satisfied.

1) 
$$\frac{\operatorname{Re}(\overline{\Delta_{1}(\varphi_{1})}(P_{\nu,2}(\varphi_{1}) - P_{\nu,1}(\varphi_{1}))) = 0,}{\operatorname{Im}(\overline{\Delta_{1}(\varphi_{1})}(P_{\nu,2}(\varphi_{1}) + P_{\nu,1}(\varphi_{1}))) = 0,} \text{ for } \nu = 0,$$
  
2) 
$$\frac{\operatorname{Re}(\overline{\Delta_{2}(\varphi_{1})}(Q_{\nu,2}(\varphi_{1}) - Q_{\nu,1}(\varphi_{1}))) = 0,}{\operatorname{Im}(\overline{\Delta_{2}(\varphi_{1})}(Q_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}))) = 0,} \text{ for } \nu < 0,$$
(2.9)

3) 
$$\frac{\operatorname{Re}(\overline{\Delta_{2}(\varphi_{1})}(Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1}) - Q_{\nu,1}(\varphi_{1}) + P_{\nu,1}(\varphi_{1}))) = 0,}{\operatorname{Im}(\overline{\Delta_{2}(\varphi_{1})}(Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1}))) = 0, \text{ for } \nu > 0.}$$

When this conditions hold the solution of the algebraic system are given by the formulas

1) If 
$$v = 0$$
,  $|P_{v,2}(\varphi_1)|^2 = |P_{v,1}(\varphi_1)|^2$ , then  
 $c_2 = b_1$ ,  

$$c_1 = \begin{cases} \frac{\text{Re } \Delta_1(\varphi_1) + i\alpha(\overline{P_{v,2}(\varphi_1)} + P_{v,1}(\varphi_1)))}{\text{Re}(P_{v,2}(\varphi_1) + P_{v,1}(\varphi_1))}, & \text{if } \text{Re}(P_{v,2}(\varphi_1) + P_{v,1}(\varphi_1)) \neq 0, \\ i\frac{\text{Re } \Delta_1(\varphi_1) - \alpha(\overline{P_{v,2}(\varphi_1)} + P_{v,1}(\varphi_1)))}{\text{Im}(P_{v,1}(\varphi_1) - P_{v,2}(\varphi_1))}, & \text{if } \text{Im}(P_{v,1}(\varphi_1) - P_{v,2}(\varphi_1)) \neq 0, \\ c_3, & \text{if } \text{Re}(P_{v,2}(\varphi_1) + P_{v,1}(\varphi_1)) = 0, \text{Im}(P_{v,1}(\varphi_1) - P_{v,2}(\varphi_1)) = 0. \end{cases}$$
(2.10)

If 
$$v < 0$$
,  $|Q_{\nu,2}(\varphi_1)|^2 = |Q_{\nu,1}(\varphi_1)|^2$ , then  
 $c_1 = b_1$ ,  

$$c_2 = \begin{cases} \frac{\text{Re } \Delta_2(\varphi_1) + i\alpha(\overline{Q_{\nu,2}(\varphi_1)} + Q_{\nu,1}(\varphi_1)))}{\text{Re}(Q_{\nu,2}(\varphi_1) + Q_{\nu,1}(\varphi_1))}, & \text{if } \text{Re}(Q_{\nu,2}(\varphi_1) + Q_{\nu,1}(\varphi_1)) \neq 0, \\ i\frac{\text{Re } \Delta_2(\varphi_1) - \alpha(\overline{Q_{\nu,2}(\varphi_1)} + Q_{\nu,1}(\varphi_1)))}{\text{Im}(Q_{\nu,1}(\varphi_1) - Q_{\nu,2}(\varphi_1))}, & \text{if } \text{Im}(Q_{\nu,1}(\varphi_1) - Q_{\nu,2}(\varphi_1)) \neq 0, \\ c_3, & \text{if } \text{Re}(Q_{\nu,2}(\varphi_1) + Q_{\nu,1}(\varphi_1)) = 0, \text{Im}(Q_{\nu,1}(\varphi_1) - Q_{\nu,2}(\varphi_1)) = 0. \end{cases}$$
(2.11)  
3) If  $v > 0$ ,  $|Q_{\nu,2}(\varphi_1) - P_{\nu,2}(\varphi_1)|^2 = |Q_{\nu,1}(\varphi_1) - P_{\nu,1}(\varphi_1)|^2$ , then  
 $c_1 = b_1 - c_2$ ,

$$c_{2} = \begin{cases} \frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) + i\alpha(\overline{Q_{\nu,2}}(\varphi_{1}) - \overline{P_{\nu,2}}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) + P_{\nu,1}(\varphi_{1}))}{\operatorname{Re}(Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1}))}, \\ if \operatorname{Re}(Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) - \alpha(\overline{Q_{\nu,2}}(\varphi_{1}) - \overline{P_{\nu,2}}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1}))}{\operatorname{Im}(-Q_{\nu,2}(\varphi_{1}) + P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1}))}, \\ if \operatorname{Im}(-Q_{\nu,2}(\varphi_{1}) + P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1})) \neq 0, \\ c_{3}, if \operatorname{Re}(Q_{\nu,2}(\varphi_{1}) - P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1})) = 0, \\ \operatorname{Im}(-Q_{\nu,2}(\varphi_{1}) + P_{\nu,2}(\varphi_{1}) + Q_{\nu,1}(\varphi_{1}) - P_{\nu,1}(\varphi_{1})) = 0, \end{cases}$$

$$(2.12)$$

where  $\alpha$  is any real,  $c_3$  is any complex number.

#### Hence, the following results holds

**Theorem 2.2.** In cases (2.8) for the solvability of problem  $D_1$  the conditions (2.9) are necessary and sufficient. Under these conditions the problem has infinitely many solutions. These solutions are given by the formulas (1.17), (2.10)-(2.12).

**Problem**  $D_2$ . Let  $\lambda \neq 1, \alpha \neq \gamma$  and  $\beta = \alpha + \gamma$ . It is required to find the solution of equation (1.1) from the class (1.3), satisfying the conditions

$$|V(r,\varphi)| = \mathcal{O}(r^{\lambda}), r \to \infty, \qquad (2.13)$$

$$V(r,\varphi_1) = b_1 r^{\lambda}, \qquad (2.14)$$

where  $b_1$  is a given complex number,  $\lambda > 0$  is a given real number.

**Solution of the problem**. For the solvability of problem  $D_2$  formula (1.33) is used. Then (2.13) automatically holds. Substituting (1.33) in the condition (2.14), we have

$$cP_2(\varphi_1) + \bar{c}P_1(\varphi_1) = \Delta(\varphi_1),$$
 (2.15)

where  $\Delta(\varphi_1) = b_1 - (BF)(\varphi_1)$ .

This equation for c has a unique solution when the condition

$$|P_2(\varphi_1)|^2 \neq |P_1(\varphi_1)|^2$$
 (2.16)

is satisfied. The solution is given by the formula

$$c = \frac{\overline{P_2(\varphi_1)}\Delta(\varphi_1) - P_1(\varphi_1)\overline{\Delta(\varphi_1)}}{|P_2(\varphi_1)|^2 - |P_1(\varphi_1)|^2}.$$
 (2.17)

Hence, the following result holds.

**Theorem 2.3**. When condition (2.16) is satisfied problem  $D_2$  has a unique solution. The unique solution is given by formulas (1.33) and (2.17).

When

$$|P_2(\varphi_1)|^2 = |P_1(\varphi_1)|^2$$
(2.18)

for the solvability of equation (2.15) the following conditions are necessary and sufficient

$$\operatorname{Re}(\Delta(\varphi_1)(P_2(\varphi_1) - P_1(\varphi_1))) = 0, \operatorname{Im}(\Delta(\varphi_1)(P_2(\varphi_1) + P_1(\varphi_1))) = 0.$$
(2.19)

When these conditions are fulfilled the solutions of equation (2.15) is given by the formula

$$c = \begin{cases} \frac{\operatorname{Re} \Delta(\varphi_{1}) + i\alpha(\overline{P_{2}(\varphi_{1})} + P_{1}(\varphi_{1}))}{\operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta(\varphi_{1}) - \alpha(\overline{P_{2}(\varphi_{1})} + P_{1}(\varphi_{1}))}{\operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ c_{1}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \end{cases}$$
(2.20)

where  $\alpha$  is any real,  $c_1$  is any complex number.

Hence, the following result holds.

**Theorem 2.4.** When the conditions (2.18) hold, for the solvability of problem  $D_2$  the equality (2.19) is necessary and sufficient. Under these conditions the problem has infinitely many solutions. These solutions are given by the formulas (1.33) and (2.20).

#### Neumann problem

**Problem**  $N_1$ . Let  $\beta \neq \alpha + \gamma$ . It is required to find the solution of equation (1.1) from the class (1.3), satisfying the conditions

$$|V(r,\varphi)| = \mathcal{O}(r^{\lambda}), r \to \infty, \qquad (2.21)$$

$$\frac{\partial V(r,\varphi)}{\partial \varphi}\Big|_{\varphi=0} = b_1 r^{\lambda} , \frac{\partial V(r,\varphi)}{\partial \varphi}\Big|_{\varphi=\varphi_1} = b_2 r^{\lambda}, \qquad (2.22)$$

where  $b_1, b_2$  are given complex numbers,  $\lambda > 0$  is a given real number.

**Solution of the problem**. For the solvability of problem  $N_1$  formulas (1.17) are used. Then (2.21) automatically holds. The functions

$$(BF)(\varphi) = \int_{0}^{\varphi} f(\varphi, \gamma) d\gamma + \int_{0}^{\varphi} b(\varphi, \gamma) \overline{(BF)(\gamma)} d\gamma, \quad P_{\nu,2}(\varphi) = I_{\nu,0}(\varphi) + \int_{0}^{\varphi} b(\varphi, \gamma) \overline{P_{\nu,1}(\gamma)} d\gamma,$$
$$P_{\nu,1}(\varphi) = \int_{0}^{\varphi} b(\varphi, \gamma) \overline{P_{\nu,2}(\gamma)} d\gamma, \quad Q_{\nu,2}(\varphi) = J_{\nu,0}(\varphi) + \int_{0}^{\varphi} b(\varphi, \gamma) \overline{Q_{\nu,1}(\gamma)} d\gamma,$$
$$Q_{\nu,1}(\varphi) = \int_{0}^{\varphi} b(\varphi, \gamma) \overline{Q_{\nu,2}(\gamma)} d\gamma$$

have the differential properties

$$\frac{\partial(BF)(\varphi)}{\partial\varphi} = \begin{cases} \int_{0}^{\varphi} f_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))d\gamma + \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{(BF)(\gamma)}d\gamma, if \nu > 0, \\ \int_{0}^{\varphi} f_{1}(\gamma)\cos(\sqrt{-\nu}(\varphi-\gamma))d\gamma + \\ + \int_{0}^{\varphi} b_{1}(\gamma)\cos(\sqrt{-\nu}(\varphi-\gamma))\overline{(BF)(\gamma)}d\gamma, if \nu < 0, \\ \int_{0}^{\varphi} f_{1}(\gamma)d\gamma + \int_{0}^{\varphi} b_{1}(\gamma)\overline{(BF)(\gamma)}d\gamma, if \nu = 0, \end{cases}$$

$$\begin{split} \frac{\partial P_{\nu,2}(\varphi)}{\partial \varphi} = \begin{cases} \sqrt{\nu} \exp(\sqrt{\nu}\varphi) + \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{P_{\nu,1}(\gamma)}d\gamma, & \text{if } \nu > 0, \\ -\sqrt{-\nu}\sin(\sqrt{-\nu}\varphi) + \int_{0}^{\varphi} b_{1}(\gamma)\cos(\sqrt{-\nu}(\varphi-\gamma))\overline{P_{\nu,1}(\gamma)}d\gamma, & \text{if } \nu < 0, \\ 1 + \int_{0}^{\varphi} b_{1}(\gamma)\overline{P_{\nu,1}(\gamma)}d\gamma, & \text{if } \nu = 0, \end{cases} \\ \\ \frac{\partial P_{\nu,1}(\varphi)}{\partial \varphi} = \begin{cases} \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{P_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu > 0, \\ \int_{0}^{\varphi} b_{1}(\gamma)\cos(\sqrt{-\nu}(\varphi-\gamma))\overline{P_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu < 0, \\ \\ \int_{0}^{\varphi} b_{1}(\gamma)\overline{P_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu = 0, \end{cases} \\ \\ \frac{\partial Q_{\nu,2}(\varphi)}{\partial \varphi} = \begin{cases} -\sqrt{\nu}\exp(-\sqrt{\nu}\varphi) + \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{Q_{\nu,1}(\gamma)}d\gamma, & \text{if } \nu > 0, \\ \\ \sqrt{-\nu}\cos(\sqrt{-\nu}\varphi) + \int_{0}^{\varphi} b_{1}(\gamma)\cos(\sqrt{-\nu}(\varphi-\gamma))\overline{Q_{\nu,1}(\gamma)}d\gamma, & \text{if } \nu < 0, \end{cases} \\ \\ \frac{\partial Q_{\nu,1}(\varphi)}{\partial \varphi} = \begin{cases} \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{Q_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu > 0, \\ \\ \int_{0}^{\varphi} b_{1}(\gamma)\overline{Q_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu = 0, \end{cases} \\ \\ \frac{\partial Q_{\nu,1}(\varphi)}{\partial \varphi} = \begin{cases} \int_{0}^{\varphi} b_{1}(\gamma)ch(\sqrt{\nu}(\varphi-\gamma))\overline{Q_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu > 0, \\ \\ \int_{0}^{\varphi} b_{1}(\gamma)\overline{Q_{\nu,2}(\gamma)}d\gamma, & \text{if } \nu = 0, \end{cases} \\ \end{cases} \end{cases}$$

Substituting (1.17) in the first of the boundary conditions (2.22), and using preceding formulas  $(BF)(\varphi)$ ,  $P_{\nu,2}(\varphi)$ ,  $P_{\nu,1}(\varphi)$ ,  $Q_{\nu,2}(\varphi)$ ,  $Q_{\nu,1}(\varphi)$ , we have

$$P_{\nu,2}(0) = \begin{cases} 1, if \ \nu > 0, \\ 1, if \ \nu < 0, \\ 0, if \ \nu = 0, \end{cases} \qquad Q_{\nu,2}(0) = \begin{cases} 1, if \ \nu > 0, \\ 0, if \ \nu < 0, \\ 1, if \ \nu = 0, \end{cases}$$

$$\frac{\partial V(r,\varphi)}{\partial \varphi} = r^{\lambda} e^{a\varphi} a((BF)(\varphi) + c_1 P_{\nu,2}(\varphi) + c_2 Q_{\nu,2}(\varphi) + \overline{c_1} P_{\nu,1}(\varphi) + \overline{c_2} Q_{\nu,1}(\varphi)) + r^{\lambda} e^{a\varphi} \left( \frac{\partial (BF)(\varphi)}{\partial \varphi} + c_1 \frac{\partial P_{\nu,2}(\varphi)}{\partial \varphi} + c_2 \frac{\partial Q_{\nu,2}(\varphi)}{\partial \varphi} + \overline{c_1} \frac{\partial P_{\nu,1}(\varphi)}{\partial \varphi} + \overline{c_2} \frac{\partial Q_{\nu,1}(\varphi)}{\partial \varphi} \right).$$

Therefore from the boundary conditions (2.22) in dependence of the sign of  $v = \frac{(4\alpha\gamma - \beta^2)\lambda^2 + 2(\beta(\alpha + \gamma) - 4\alpha\gamma)\lambda - (\alpha - \gamma)^2}{q^2}$  the following different

algebraic systems for  $c_1$  and  $c_2$  occur.

1) If v > 0, then

$$c_{1} = \frac{b_{1} - (a - \sqrt{\nu})c_{2}}{(a + \sqrt{\nu})}, \quad c_{2}T_{1}(\varphi_{1}) + \overline{c}_{2}T_{2}(\varphi_{1}) = \Delta(\varphi_{1}),$$

where 
$$\Delta(\varphi_{1}) = b_{2} \exp(-a\varphi) - a(BF)(\varphi_{1}) - \frac{\partial(BF)(\varphi_{1})}{\partial\varphi} - \frac{b_{1}}{\partial\varphi} \left(aP_{\nu,2}(\varphi_{1}) + \frac{\partial P_{\nu,2}(\varphi_{1})}{\partial\varphi}\right) - \frac{\overline{b_{1}}}{(-a+\sqrt{\nu})} \left(aP_{\nu,1}(\varphi_{1}) + \frac{\partial P_{\nu,1}(\varphi_{1})}{\partial\varphi}\right),$$
$$T_{1}(\varphi_{1}) = \left(\left(aQ_{\nu,2}(\varphi_{1}) + \frac{\partial Q_{\nu,2}(\varphi_{1})}{\partial\varphi}\right) - \frac{(a-\sqrt{\nu})}{(a+\sqrt{\nu})} \left(aP_{\nu,2}(\varphi_{1}) + \frac{\partial P_{\nu,2}(\varphi_{1})}{\partial\varphi}\right)\right),$$
$$T_{2}(\varphi_{1}) = \left(\left(aQ_{\nu,1}(\varphi_{1}) + \frac{\partial Q_{\nu,1}(\varphi_{1})}{\partial\varphi}\right) + \frac{(a+\sqrt{\nu})}{(-a+\sqrt{\nu})} \left(aP_{\nu,1}(\varphi_{1}) + \frac{\partial P_{\nu,1}(\varphi_{1})}{\partial\varphi}\right)\right).$$

2) If v < 0, then

$$c_2 = \frac{b_1 - ac_1}{\sqrt{-\nu}}, \quad c_1 T_3(\varphi_1) + \overline{c}_1 T_4(\varphi_1) = \Delta_1(\varphi_1),$$

where 
$$\Delta_{1}(\varphi_{1}) = b_{2} \exp(-a\varphi) - a(BF)(\varphi_{1}) - \frac{\partial(BF)(\varphi_{1})}{\partial\varphi} - \frac{b_{1}}{\sqrt{-\nu}} \left(aQ_{\nu,2}(\varphi_{1}) + \frac{\partial Q_{\nu,2}(\varphi_{1})}{\partial\varphi}\right) - \frac{\overline{b_{1}}}{\sqrt{-\nu}} \left(aQ_{\nu,1}(\varphi_{1}) + \frac{\partial Q_{\nu,1}(\varphi_{1})}{\partial\varphi}\right),$$
$$T_{3}(\varphi_{1}) = \left(\left(aP_{\nu,2}(\varphi_{1}) + \frac{\partial P_{\nu,2}(\varphi_{1})}{\partial\varphi}\right) - \frac{a}{\sqrt{-\nu}} \left(aQ_{\nu,2}(\varphi_{1}) + \frac{\partial Q_{\nu,2}(\varphi_{1})}{\partial\varphi}\right)\right),$$
$$T_{4}(\varphi_{1}) = \left(\left(aP_{\nu,1}(\varphi_{1}) + \frac{\partial P_{\nu,1}(\varphi_{1})}{\partial\varphi}\right) + \frac{a}{\sqrt{-\nu}} \left(aQ_{\nu,1}(\varphi_{1}) + \frac{\partial Q_{\nu,1}(\varphi_{1})}{\partial\varphi}\right)\right).$$

3) If 
$$v = 0$$
, then  
 $c_1 = b_1 - ac_2$ ,  $c_2T_5(\varphi_1) + \overline{c}_2T_6(\varphi_1) = \Delta_2(\varphi_1)$ ,  
where  $\Delta_2(\varphi_1) = b_2 \exp(-a\varphi) - a(BF)(\varphi_1) - \frac{\partial(BF)(\varphi_1)}{\partial\varphi} - b_1\left(aP_{v,2}(\varphi_1) + \frac{\partial P_{v,2}(\varphi_1)}{\partial\varphi}\right) - \overline{b_1}\left(aP_{v,1}(\varphi_1) + \frac{\partial P_{v,1}(\varphi_1)}{\partial\varphi}\right)$ ,  
 $T_5(\varphi_1) = \left(\left(aQ_{v,2}(\varphi_1) + \frac{\partial Q_{v,2}(\varphi_1)}{\partial\varphi}\right) - a\left(aP_{v,2}(\varphi_1) + \frac{\partial P_{v,2}(\varphi_1)}{\partial\varphi}\right)\right)$ ,  
 $T_6(\varphi_1) = \left(\left(aQ_{v,1}(\varphi_1) + \frac{\partial Q_{v,1}(\varphi_1)}{\partial\varphi}\right) + a\left(aP_{v,1}(\varphi_1) + \frac{\partial P_{v,1}(\varphi_1)}{\partial\varphi}\right)\right)$ .

Each of these systems has a unique solution when the conditions

1) 
$$\nu > 0$$
,  $|T_1(\varphi_1)|^2 \neq |T_2(\varphi_1)|^2$ ,  
2)  $\nu < 0$ ,  $|T_3(\varphi_1)|^2 \neq |T_4(\varphi_1)|^2$ ,  
3)  $\nu = 0$ ,  $|T_5(\varphi_1)|^2 \neq |T_6(\varphi_1)|^2$ ,  
(2.23)

hold respectively. Under these conditions the solutions are given by the formulas

1) If 
$$v > 0$$
,  $|T_1(\varphi_1)|^2 \neq |T_2(\varphi_1)|^2$ , then  
 $c_1 = \frac{b_1 - (a - \sqrt{v})c_2}{(a + \sqrt{v})}, c_2 = \frac{\overline{\Delta(\varphi_1)}T_2(\varphi_1) - \Delta(\varphi_1)\overline{T_1(\varphi_1)}}{|T_2(\varphi_1)|^2 - |T_1(\varphi_1)|^2}.$ 
(2.24)  
2) If  $v < 0$ ,  $|T_3(\varphi_1)|^2 \neq |T_4(\varphi_1)|^2$ , then

$$c_{2} = \frac{b_{1} - ac_{1}}{\sqrt{-v}}, c_{1} = \frac{\overline{\Delta_{1}(\varphi_{1})}T_{4}(\varphi_{1}) - \Delta_{1}(\varphi_{1})\overline{T_{3}(\varphi_{1})}}{|T_{4}(\varphi_{1})|^{2} - |T_{3}(\varphi_{1})|^{2}}.$$
(2.25)  
3) If  $v = 0, |T_{5}(\varphi_{1})|^{2} \neq |T_{6}(\varphi_{1})|^{2}$ , then  

$$c_{2} = \frac{\overline{\Delta_{2}(\varphi_{1})}T_{6}(\varphi_{1}) - \Delta_{2}(\varphi_{1})\overline{T_{5}(\varphi_{1})}}{|T_{6}(\varphi_{1})|^{2} - |T_{5}(\varphi_{1})|^{2}}, c_{1} = b_{1} - ac_{2}.$$
(2.26)

Hence, the following result holds

**Theorem 2.5.** Problem  $N_1$  has a unique solution when one of the conditions (2.23) holds. In this case the unique solutions are given by the formulas (1.17), (2.24)-(2.26), respectively.

In the cases

1) 
$$\nu > 0$$
,  $|T_1(\varphi_1)|^2 = |T_2(\varphi_1)|^2$ ,  
2)  $\nu < 0$ ,  $|T_3(\varphi_1)|^2 = |T_4(\varphi_1)|^2$ ,  
3)  $\nu = 0$ ,  $|T_5(\varphi_1)|^2 = |T_6(\varphi_1)|^2$ 
(2.27)

For the solvability of the indicated algebraic system the following conditions are necessary and suffusient

`

1) 
$$\begin{aligned} &\operatorname{Re}\left(\overline{\Delta(\varphi_{1})}\left(T_{1}(\varphi_{1})-T_{2}(\varphi_{1})\right)\right)=0, & if \quad \nu > 0, \\ &\operatorname{Im}\left(\overline{\Delta(\varphi_{1})}\left(T_{1}(\varphi_{1})+T_{2}(\varphi_{1})\right)\right)=0, & if \quad \nu > 0, \\ &\operatorname{Re}\left(\overline{\Delta_{1}(\varphi_{1})}\left(T_{3}(\varphi_{1})-T_{4}(\varphi_{1})\right)\right)=0, & if \quad \nu < 0, \\ &\operatorname{Im}\left(\overline{\Delta_{1}(\varphi_{1})}\left(T_{3}(\varphi_{1})+T_{4}(\varphi_{1})\right)\right)=0, & if \quad \nu < 0, \\ &\operatorname{Sh}\left(\overline{\Delta_{2}(\varphi_{1})}\left(T_{5}(\varphi_{1})-T_{6}(\varphi_{1})\right)\right)=0, & if \quad \nu = 0. \end{aligned}$$

$$(2.28)$$

When these conditions hold then the solutions of the indicated algebraic systems are given by the formulas

1) If v > 0,  $|T_1(\varphi_1)|^2 = |T_2(\varphi_1)|^2$ , then

$$c_{1} = \frac{b_{1} - (a - \sqrt{v})c_{2}}{(a + \sqrt{v})},$$

$$c_{2} = \begin{cases} \frac{\operatorname{Re}\Delta(\varphi_{1}) + i\alpha(\overline{T_{1}(\varphi_{1})} + T_{2}(\varphi_{1}))}{\operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1}))}, & \text{if } \operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re}\Delta(\varphi_{1}) - \alpha(\overline{T_{1}(\varphi_{1})} + T_{2}(\varphi_{1}))}{\operatorname{Im}(T_{2}(\varphi_{1}) - T_{1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(T_{1}(\varphi_{1}) - T_{2}(\varphi_{1})) \neq 0, \\ c_{3}, & \text{if } \operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) = 0, \operatorname{Im}(T_{1}(\varphi_{1}) - T_{2}(\varphi_{1})) = 0. \end{cases}$$

$$(2.29)$$

2) If 
$$v < 0$$
,  $|T_{3}(\varphi_{1})|^{2} = |T_{4}(\varphi_{1})|^{2}$ , then  

$$c_{2} = \frac{b_{1} - ac_{1}}{\sqrt{-v}},$$

$$c_{1} = \begin{cases} \frac{\operatorname{Re} \Delta_{1}(\varphi_{1}) + i\alpha(\overline{T_{3}(\varphi_{1})} + T_{4}(\varphi_{1}))}{\operatorname{Re}(T_{3}(\varphi_{1}) + T_{4}(\varphi_{1}))}, & \text{if } \operatorname{Re}(T_{3}(\varphi_{1}) + T_{4}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{1}(\varphi_{1}) - \alpha(\overline{T_{3}(\varphi_{1})} + T_{4}(\varphi_{1}))}{\operatorname{Im}(T_{4}(\varphi_{1}) - T_{3}(\varphi_{1}))}, & \text{if } \operatorname{Im}(T_{3}(\varphi_{1}) - T_{4}(\varphi_{1})) \neq 0, \\ c_{3}, & \text{if } \operatorname{Re}(T_{3}(\varphi_{1}) + T_{4}(\varphi_{1})) = 0, \operatorname{Im}(T_{3}(\varphi_{1}) - T_{4}(\varphi_{1})) = 0. \end{cases}$$

$$(2.30)$$

3) If 
$$v = 0$$
,  $|T_{5}(\varphi_{1})|^{2} = |T_{6}(\varphi_{1})|^{2}$ , then  

$$c_{1} = b_{1} - ac_{2},$$

$$c_{2} = \begin{cases} \frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) + i\alpha(\overline{T_{5}(\varphi_{1})} + T_{6}(\varphi_{1}))}{\operatorname{Re}(T_{5}(\varphi_{1}) + T_{6}(\varphi_{1}))}, & \text{if } \operatorname{Re}(T_{5}(\varphi_{1}) + T_{6}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) - \alpha(\overline{T_{5}(\varphi_{1})} + T_{6}(\varphi_{1}))}{\operatorname{Im}(T_{6}(\varphi_{1}) - T_{5}(\varphi_{1}))}, & \text{if } \operatorname{Im}(T_{5}(\varphi_{1}) - T_{6}(\varphi_{1})) \neq 0, \\ c_{3}, & \text{if } \operatorname{Re}(T_{5}(\varphi_{1}) + T_{6}(\varphi_{1})) = 0, \operatorname{Im}(T_{5}(\varphi_{1}) - T_{6}(\varphi_{1})) = 0, \end{cases}$$

$$(2.31)$$

where  $\alpha$  is any real,  $c_3$  is any complex number.

Hence, the following result holds.

**Theorem 2.6.** In the cases (2.27) for the solvability of problem  $N_1$  condition (2.28) is necessary and sufficient. Under these conditions the problem has infinitely many solutions. These solutions are given by the formulas (1.17), (2.29)-(2.31), respectively.

**Problem**  $N_2$ . Let  $\lambda \neq 1, \alpha \neq \gamma$  and  $\beta = \alpha + \gamma$ . It is required to find the solution of equation (1.1), from the class (1.3), satisfying the conditions

$$|V(r,\varphi)| = O(r^{\lambda}), r \to \infty, \qquad (2.32)$$

$$\left. \frac{\partial V(r,\phi)}{\partial \phi} \right|_{\phi=\phi_1} = b_2 r^{\lambda} , \qquad (2.33)$$

where  $b_2$  is a given complex number,  $\lambda > 0$  is a given real number.

For the solution of problem  $N_2$  formula (1.33) is used. Then (2.32) automatically holds. From the form of the functions  $(BF)(\varphi)$ ,  $P_1(\varphi)$ ,  $P_2(\varphi)$  follows

$$\frac{\partial(BF)(\phi)}{\partial \phi} = f_1(\phi) + b_1(\phi)\overline{(BF)(\phi)} - i\nu(BF)(\phi),$$

$$\frac{\partial P_2(\phi)}{\partial \phi} = b_1(\phi)\overline{P_1(\phi)} - i\nu P_2(\phi),$$

$$\frac{\partial P_1(\phi)}{\partial \phi} = b_1(\phi)\overline{P_2(\phi)} - i\nu P_1(\phi).$$
(2.34)

Substituting (1.33) in the boundary condition (2.33), we have in view of (2.34)

$$cT_2(\varphi_1) + \bar{c}T_1(\varphi_1) = \Delta_1(\varphi_1),$$
 (2.35)

where

$$T_2(\varphi_1) = \left(b_1(\varphi_1)\overline{P_1(\varphi_1)} - i\nu P_2(\varphi_1)\right), \ T_1(\varphi_1) = \left(b_1(\varphi_1)\overline{P_2(\varphi_1)} - i\nu P_1(\varphi_1)\right),$$
  
$$\Delta_1(\varphi_1) = b_2 - f_1(\varphi_1) - b_1(\varphi_1)\overline{(BF)(\varphi_1)} + i\nu(BF)(\varphi_1).$$

Equation (2.35) for the unknown c has a unique solution when

$$|T_1(\varphi_1)|^2 \neq |T_2(\varphi_1)|^2,$$
 (2.36)

which is given by the formula

$$c = \frac{\Delta_1(\varphi_1)T_2(\varphi_1) - \Delta_1(\varphi_1)T_1(\varphi_1)}{\left|T_2(\varphi_1)\right|^2 - \left|T_1(\varphi_1)\right|^2}.$$
(2.37)

Thus, the following result holds.

**Theorem 2.7.** When the condition (2.36) is satisfied, problem  $N_2$  has a unique solution. This solution is given by the formulas (1.33), (2.37).

In case, when

$$|T_2(\varphi_1)|^2 = |T_1(\varphi_1)|^2$$
 (2.38)

for the solvability of equation (2.35) the conditions

$$\operatorname{Re}\left(\overline{\Delta_{1}(\varphi_{1})}(T_{2}(\varphi_{1}) - T_{1}(\varphi_{1}))\right) = 0, \operatorname{Im}\left(\overline{\Delta_{1}(\varphi_{1})}(T_{2}(\varphi_{1}) + T_{1}(\varphi_{1}))\right) = 0. \quad (2.39)$$

are necessary and sufficient. When these conditions hold the solution of equation (2.35) is given by the formulas

$$c = \begin{cases} \frac{\operatorname{Re} \Delta_{1} + i\alpha(\overline{T_{2}(\varphi_{1})} + T_{1}(\varphi_{1}))}{\operatorname{Re}(T_{2}(\varphi_{1}) + T_{1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(T_{2}(\varphi_{1}) + T_{1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{1} - \alpha(\overline{T_{2}(\varphi_{1})} + T_{1}(\varphi_{1}))}{\operatorname{Im}(-T_{2}(\varphi_{1}) + T_{1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(T_{2}(\varphi_{1}) - T_{1}(\varphi_{1})) \neq 0, \\ c_{2}, & \text{if } \operatorname{Re}(T_{2}(\varphi_{1}) + T_{1}(\varphi_{1})) = 0, \operatorname{Im}(T_{2}(\varphi_{1}) - T_{1}(\varphi_{1})) = 0, \end{cases}$$
(2.40)

where  $\alpha$  is any real,  $c_2$  is any complex number.

Thus, the following result holds.

**Theorem 2.8.** When the condition (2.38) holds, for the solvability of problem  $N_2$  equalities (2.39) are necessary and sufficient. Under these conditions the problem has infinitely many solutions. These solutions are given by the formulas (1.33) and (2.40).

## 2.2 Initial boundary problem for nonhomogeneous model second order partial differential equations in the plane with Fuchs operator in the main part

**Problem**  $K_1$ . Let  $\beta \neq \alpha + \gamma$ . It is required to find the solution of equation (1.34) from the class (1.35), satisfying the conditions

$$\frac{\partial^k}{\partial p^k} V(r, \varphi) \bigg|_{\substack{r=0\\\varphi=0}} = a_k, \quad 0 \le k,$$
(2.41)

$$\frac{\partial^{k}}{\partial p^{k}} \frac{\partial V(r,\varphi)}{\partial \varphi} \bigg|_{\substack{r=0\\\varphi=0}} = b_{k}, \quad 0 \le k,$$
(2.42)

where  $p = r^{\nu}$ ;  $a_k, b_k, 0 \le k$  are given complex numbers, so that the series  $\sum_{k=1}^{\infty} \frac{a_k}{k!} r^{\nu k}, \sum_{k=1}^{\infty} \frac{b_k}{k!} r^{\nu k} \text{ are convergent in } G.$ 

#### Solution of the problem

The functions 
$$(BF)_k(\varphi) = \int_0^{\varphi} f_k(\varphi, \gamma) d\gamma + \int_0^{\varphi} b_k(\varphi, \gamma) \overline{(BF)_k(\gamma)} d\gamma$$
,

$$P_{k,2}(\varphi) = I_{k,0}(\varphi) + \int_{0}^{\varphi} b_{k}(\varphi,\gamma) \overline{P_{k,1}(\gamma)} d\gamma, \quad P_{k,1}(\varphi) = \int_{0}^{\varphi} b_{k}(\varphi,\gamma) \overline{P_{k,2}(\gamma)} d\gamma,$$

$$Q_{k,2}(\varphi) = J_{k,0}(\varphi) + \int_{0}^{\varphi} b_{k}(\varphi,\gamma) \overline{Q_{k,1}(\gamma)} d\gamma, \quad Q_{k,1}(\varphi) = \int_{0}^{\varphi} b_{k}(\varphi,\gamma) \overline{Q_{k,2}(\gamma)} d\gamma$$

have the differential properties

$$\frac{\partial (BF)_0(\varphi)}{\partial \varphi} = \int_0^{\varphi} f_{0,1}(\gamma) \exp(\tau_0(\varphi - \gamma)) d\gamma + \int_0^{\varphi} b_0(\gamma) \exp(\tau_0(\varphi - \gamma)) \overline{(BF)_0(\gamma)} d\gamma,$$
$$\frac{\partial P_{0,2}(\varphi)}{\partial \varphi} = \tau_0 \exp(\tau_0 \varphi) + \int_0^{\varphi} b_0(\gamma) \exp(\tau_0(\varphi - \gamma)) \overline{P_{0,1}(\gamma)} d\gamma,$$

$$\begin{split} \frac{\partial P_{0,1}(\varphi)}{\partial \varphi} &= \int_{0}^{\varphi} b_{0}(\gamma) \exp(\tau_{0}(\varphi - \gamma)) \overline{P_{0,2}(\gamma)} d\gamma, \\ \frac{\partial Q_{0,2}(\varphi)}{\partial \varphi} &= \int_{0}^{\varphi} b_{0}(\gamma) \exp(\tau_{0}(\varphi - \gamma)) \overline{Q_{0,1}(\gamma)} d\gamma, \\ \frac{\partial Q_{0,1}(\varphi)}{\partial \varphi} &= \int_{0}^{\varphi} b_{0}(\gamma) \exp(\tau_{0}(\varphi - \gamma)) \overline{Q_{0,2}(\gamma)} d\gamma, \\ \frac{\partial Q_{0,1}(\varphi)}{\partial \varphi} &= \int_{0}^{\varphi} b_{0}(\gamma) \exp(\tau_{0}(\varphi - \gamma)) \overline{Q_{0,2}(\gamma)} d\gamma, \\ \frac{\partial Q_{0,1}(\varphi)}{\partial \varphi} &= \begin{cases} \int_{0}^{\varphi} f_{k,1}(\gamma) ch(\sqrt{\tau_{k}}(\varphi - \gamma)) (\overline{BF})_{k}(\gamma) d\gamma, & \text{if } \tau_{k} > 0, \\ \int_{0}^{\varphi} f_{k,1}(\gamma) \cos(\sqrt{-\tau_{k}}(\varphi - \gamma)) (\overline{BF})_{k}(\gamma) d\gamma, & \text{if } \tau_{k} < 0, \\ \int_{0}^{\varphi} f_{k,1}(\gamma) d\gamma + \int_{0}^{\varphi} b_{k}(\gamma) (\overline{BF})_{k}(\gamma) d\gamma, & \text{if } \tau_{k} < 0, \\ \int_{0}^{\varphi} f_{k,1}(\gamma) d\gamma + \int_{0}^{\varphi} b_{k}(\gamma) (\overline{BF})_{k}(\gamma) d\gamma, & \text{if } \tau_{k} > 0, \end{cases} \\ \frac{\partial P_{k,2}(\varphi)}{\partial \varphi} &= \begin{cases} \sqrt{\tau_{k}} \exp(\sqrt{\tau_{k}}\varphi) + \int_{0}^{\varphi} b_{k}(\gamma) (\overline{BF})_{k}(\gamma) d\gamma, & \text{if } \tau_{k} < 0, \\ -\sqrt{-\tau_{k}} \sin(\sqrt{-\tau_{k}}\varphi) + \int_{0}^{\varphi} b_{k}(\gamma) \cos(\sqrt{-\tau_{k}}(\varphi - \gamma)) \overline{P_{k,1}(\gamma)} d\gamma, & \text{if } \tau_{k} < 0, \\ 1 + \int_{0}^{\varphi} b_{k}(\gamma) \overline{P_{k,1}(\gamma)} d\gamma, & \text{if } \tau_{k} = 0, \end{cases} \\ \frac{\partial P_{k,1}(\varphi)}{\partial \varphi} &= \begin{cases} \int_{0}^{\varphi} b_{k}(\gamma) ch(\sqrt{\tau_{k}}(\varphi - \gamma)) \overline{P_{k,2}(\gamma)} d\gamma, & \text{if } \tau_{k} > 0, \\ 1 + \int_{0}^{\varphi} b_{k}(\gamma) ch(\sqrt{\tau_{k}}(\varphi - \gamma)) \overline{P_{k,2}(\gamma)} d\gamma, & \text{if } \tau_{k} < 0, \\ \int_{0}^{\varphi} b_{k}(\gamma) \cos(\sqrt{-\tau_{k}}(\varphi - \gamma)) \overline{P_{k,2}(\gamma)} d\gamma, & \text{if } \tau_{k} < 0, \\ \int_{0}^{\varphi} b_{k}(\gamma) \cos(\sqrt{-\tau_{k}}(\varphi - \gamma)) \overline{P_{k,2}(\gamma)} d\gamma, & \text{if } \tau_{k} < 0, \end{cases} \end{cases}$$

$$\frac{\partial Q_{k,2}(\varphi)}{\partial \varphi} = \begin{cases} -\sqrt{\tau_k} \exp(\sqrt{\tau_k}\varphi) + \int_0^{\varphi} b_k(\gamma) ch(\sqrt{\tau_k}(\varphi - \gamma))\overline{Q_{k,1}(\gamma)}d\gamma, if \ \tau_k > 0, \\ \sqrt{-\tau_k} \cos(\sqrt{-\tau_k}\varphi) + \int_0^{\varphi} b_k(\gamma) \cos(\sqrt{-\tau_k}(\varphi - \gamma))\overline{Q_{k,1}(\gamma)}d\gamma, if \ \tau_k < 0, \\ \int_0^{\varphi} b_k(\gamma)\overline{Q_{k,1}(\gamma)}d\gamma, if \ \tau_k = 0, \end{cases}$$
$$\frac{\partial Q_{k,1}(\varphi)}{\partial \varphi} = \begin{cases} \int_0^{\varphi} b_k(\gamma) ch(\sqrt{\tau_k}(\varphi - \gamma))\overline{Q_{k,2}(\gamma)}d\gamma, if \ \tau_k > 0, \\ \int_0^{\varphi} b_k(\gamma) \cos(\sqrt{-\tau_k}(\varphi - \gamma))\overline{Q_{k,2}(\gamma)}d\gamma, if \ \tau_k < 0, \\ \int_0^{\varphi} b_k(\gamma)\overline{Q_{k,2}(\gamma)}d\gamma, if \ \tau_k = 0, \end{cases}$$

From these equalities and the functions  $(BF)_k(\varphi)$ ,  $P_{k,2}(\varphi)$ ,  $P_{k,1}(\varphi)$ ,  $Q_{k,2}(\varphi)$ ,  $Q_{k,1}(\varphi)$ , also the numbers

$$\tau_{k} = \frac{(vk)^{2}(4\alpha\gamma - \beta^{2}) - vk(8\alpha\gamma - 2\alpha\beta - 2\beta\gamma) - (\alpha - \gamma)^{2}}{q^{2}}, \ 1 \le k, \text{ are determined:}$$

$$(BF)_{0}(0) = P_{0,1}(0) = Q_{0,1}(0) = 0, \quad P_{0,2}(0) = Q_{0,2}(0) = 1,$$
  
$$(BF)_{k}(0) = P_{k,1}(0) = Q_{k,1}(0) = 0,$$

$$P_{k,2}(0) = \begin{cases} 1, & \text{if } \tau_k > 0, \\ 1, & \text{if } \tau_k < 0, \\ 0, & \text{if } \tau_k = 0, \end{cases} \qquad Q_{k,2}(0) = \begin{cases} 1, & \text{if } \tau_k > 0, \\ 0, & \text{if } \tau_k < 0, \\ 1, & \text{if } \tau_k = 0, \end{cases} \qquad 1 \le k,$$

$$\frac{\partial(BF)_{0}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \frac{\partial P_{0,1}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \frac{\partial Q_{0,1}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \frac{\partial Q_{0,2}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = 0,$$

$$\frac{\partial P_{0,2}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \tau_{0}, \quad \frac{\partial(BF)_{k}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \frac{\partial P_{k,1}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \frac{\partial Q_{k,1}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = 0,$$

$$\frac{\partial P_{k,2}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \begin{cases}
\sqrt{\tau_{k}}, if \ \tau_{k} > 0, \\
0, if \ \tau_{k} < 0, \\
1, if \ \tau_{k} = 0,
\end{cases}
\frac{\partial Q_{k,2}(\varphi)}{\partial\varphi}\Big|_{\varphi=0} = \begin{cases}
-\sqrt{\tau_{k}}, if \ \tau_{k} > 0, \\
0, if \ \tau_{k} < 0, \\
0, if \ \tau_{k} = 0,
\end{cases}$$
(2.43)

The coefficients  $c_{k,1}$  and  $c_{k,2}$ ,  $0 \le k$ , we take so that the function is given by formula (1.50) satisfying the conditions (2.41) and (2.42). For this, substituting (1.50) in (2.41) and (2.42), we have in view of (2.43)

$$c_{0,1} = \frac{b_0}{\tau_0} , \quad c_{0,2} = a_0 - \frac{b_0}{\tau_0},$$

$$c_{k,1} = \begin{cases} \frac{a_k \sqrt{\tau_k} + b_k}{2\sqrt{\tau_k}}, & \text{if } \tau_k > 0, \\ a_k, & \text{if } \tau_k < 0, \\ b_k, & \text{if } \tau_k = 0, \end{cases} \quad c_{k,2} = \begin{cases} \frac{a_k \sqrt{\tau_k} - b_k}{2\sqrt{\tau_k}}, & \text{if } \tau_k > 0, \\ \frac{b_k}{\sqrt{\tau_k}}, & \text{if } \tau_k < 0, \\ a_k, & \text{if } \tau_k = 0, \end{cases}$$

$$(2.44)$$

 $1 \leq k$ .

Thus, the following result holds.

**Theorem 2.9.** Let  $\beta \neq \alpha + \gamma$ . Then the problem  $K_1$  has a unique solution. The unique solution is given by formulas (1.50) and (2.44).

**Problem**  $K_2$ . Let  $\beta = \alpha + \gamma$ . It is required to find the solution of equation (1.34) from the class (1.35), satisfying the conditions

$$\left. \frac{\partial^k}{\partial p^k} V(r, \varphi) \right|_{\substack{r=0\\\varphi=1}} = a_k, \quad 0 \le k,$$
(2.45)

where  $p = r^{\nu}$ ,  $a_k, 0 \le k$ , are given complex numbers, so that the series  $\sum_{k=1}^{\infty} \frac{a_k}{k!} r^{\nu k} \text{ is convergent in } G.$ 

**Solution of the problem.** Substituting (2.45) in (1.68), we have

$$c_k P_{k,2}(\varphi_1) + \bar{c}_k P_{k,1}(\varphi_1) = \Delta_k(\varphi_1), \qquad (2.46)$$

where  $\Delta_{k}(\varphi_{1}) = a_{k} - F_{k,1}(\varphi_{1}).$ 

Equation (2.46) for  $c_k$  has a unique solution when

$$\Delta_{k}(\varphi_{1}) = \left| P_{k,2}(\varphi_{1}) \right|^{2} - \left| P_{k,1}(\varphi_{1}) \right|^{2} \neq 0.$$
(2.47)

This solution is given by the following formula

$$c_{k} = \frac{\overline{P_{k,2}(\varphi_{1})} \cdot \Delta_{k}(\varphi_{1}) - P_{k,1}(\varphi_{1}) \cdot \overline{\Delta_{k}(\varphi_{1})}}{\left|P_{k,2}(\varphi_{1})\right|^{2} - \left|P_{k,1}(\varphi_{1})\right|^{2}}.$$
(2.48)

When

$$\Delta_k(\varphi_1) = 0 \tag{2.49}$$

for the solvability of equation (2.46) the conditions

$$\operatorname{Re}(\overline{\Delta_{k}(\varphi_{1})}(P_{k,2}(\varphi_{1}) - P_{k,1}(\varphi_{1}))) = 0, \operatorname{Im}(\overline{\Delta_{k}(\varphi_{1})}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))) = 0$$
(2.50)

are necessary and sufficient. When these conditions hold the solution of equation (2.46) is

$$c_{k} = \begin{cases} \frac{\operatorname{Re}\Delta_{k}(\varphi_{1}) + i\alpha_{k}(\overline{P_{k,2}}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}{\operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re}\Delta_{k}(\varphi_{1}) - \alpha_{k}(\overline{P_{k,2}}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}{\operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) \neq 0, \end{cases}$$
(2.51)  
$$c_{k,1}, & \text{if } \operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) = 0, \\ \operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}$$

where  $\alpha_k$  are any real,  $c_{k,1}$  are any complex numbers.

Thus, the following result holds.

**Theorem 2.10.** 1) When  $\Delta_k(\varphi_1) \neq 0$ ,  $0 \leq k$ , the problem  $K_2$  has a unique solution. This solution is given by formulas (1.68) and (2.48).

2) If for some index k the equality  $\Delta_k(\varphi_1) = 0$  holds, then for the solvability of problem  $K_2$  the condition (2.50) for this particular index k is necessary and sufficient. In this case the problem has infinitely many solutions. These solutions are given by formula (1.68), where  $c_{\kappa}$  is defined by formulas (2.48) if  $\Delta_k(\varphi_1) \neq 0$ and by formulas (2.51) if  $\Delta_k(\varphi_1) = 0$ . 2.3 Dirichlet problem with given growth at infinity for second order partial differential equations in the plane with Fuchs operator in the main part and specified right hand side.

Consider the Dirichlet problem for equation (1.69).

**Problem**  $D_3$ . Let  $b(\varphi) \neq a(\varphi) + c(\varphi)$ . It is required to find the solution of equation (1.69) from the class (1.3), satisfying the conditions

$$|V(r,\varphi)| = \mathcal{O}(r^{\lambda}), r \to \infty, \qquad (2.52)$$

$$V(r,0) = b_1 r^{\lambda}, \ V(r,\varphi_1) = b_2 r^{\lambda}, \tag{2.53}$$

where  $b_1, b_2$  are given complex numbers,  $\lambda > 0$  is a given real number.

**Solution of the problem**. For solving problem  $D_3$  formula (1.80) is used. Then (2.52) automatically holds. For the functions  $F_1(\varphi)$ ,  $P_1(\varphi)$ ,  $P_2(\varphi)$ ,  $Q_1(\varphi)$ ,  $Q_2(\varphi)$  follows

$$F_1(0) = 0, P_1(0) = 0, Q_1(0) = 0, P_2(0) = \psi_1(0), Q_2(0) = \psi_2(0).$$

Therefore from the boundary conditions (2.53) follows the algebraic system of equations for  $c_1$  and  $c_2$ ,

$$c_{1}\psi_{1}(0) + c_{2}\psi_{2}(0) = b_{1},$$
  

$$c_{2}T_{1}(\varphi_{1}) + \overline{c}_{2}T_{2}(\varphi_{1}) = \Delta_{1}(\varphi_{1}),$$
(2.54)

where if  $\psi_1(0) \neq 0$ ,

$$\Delta_1(\varphi_1) = b_2 - F_1(\varphi_1) - \frac{b_1}{\psi_1(0)} P_2(\varphi_1) - \frac{\overline{b_1}}{\overline{\psi_1(0)}} P_1(\varphi_1),$$

$$T_1(\varphi_1) = Q_2(\varphi_1) - \frac{\psi_2(0)}{\psi_1(0)} P_2(\varphi_1), \quad T_2(\varphi_1) = Q_1(\varphi_1) - \frac{\psi_2(0)}{\psi_1(0)} P_1(\varphi_1).$$

System (2.54) has a unique solution in case, when

$$\Lambda_1(\varphi_1) = |T_1(\varphi_1)|^2 - |T_2(\varphi_1)|^2 \neq 0.$$
(2.55)

Under this condition the solution is given as

$$c_{2} = \frac{\Delta_{1}(\varphi_{1})\overline{T_{1}(\varphi_{1})} - \overline{\Delta_{1}(\varphi_{1})}\overline{T_{2}(\varphi_{1})}}{\left|T_{1}(\varphi_{1})\right|^{2} - \left|T_{2}(\varphi_{1})\right|^{2}}, \qquad c_{1} = \frac{b_{1} - c_{2}\psi_{2}(0)}{\psi_{1}(0)}.$$
(2.56)

In case, when

$$\Lambda_1(\varphi_1) = 0 \tag{2.57}$$

for the solvability of the algebraic system (2.54) the conditions

$$Re(\Delta_{1}(T_{1}(\varphi_{1}) - T_{2}(\varphi_{1}))) = 0,$$
  

$$Im(\overline{\Delta_{1}}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1}))) = 0,$$
(2.58)

are necessary and sufficient. When these conditions hold the solutions of the algebraic system (2.54) are

$$c_{2} = \begin{cases} \frac{\operatorname{Re} \Delta_{1}(\varphi_{1}) + i\alpha(\overline{T_{1}(\varphi_{1})} + T_{2}(\varphi_{1}))}{\operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1}))}, & \text{if } \operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{1}(\varphi_{1}) - \alpha(\overline{T_{1}(\varphi_{1})} + T_{2}(\varphi_{1}))}{\operatorname{Im}(-T_{1}(\varphi_{1}) + T_{2}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) \neq 0, \\ c_{3}, & \text{if } \operatorname{Re}(T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) = 0, & \operatorname{Im}(-T_{1}(\varphi_{1}) + T_{2}(\varphi_{1})) = 0, \end{cases}$$
(2.59)

where  $\alpha$  is any real,  $c_3$  is any complex number.

When  $\psi_1(0) = 0$  but  $\psi_2(0) \neq 0$  we have

$$c_{2} = \frac{b_{1}}{\psi_{2}(0)},$$

$$c_{1}P_{2}(\varphi_{1}) + \bar{c}_{2}P_{1}(\varphi_{1}) = \Delta_{2}(\varphi_{1}),$$
(2.60)

where 
$$\Delta_2(\varphi_1) = b_2 - F_1(\varphi_1) - \frac{b_1}{\psi_2(0)}Q_2(\varphi_1) - \frac{b_1}{\overline{\psi_2(0)}}Q_1(\varphi_1),$$

If  $\psi_1(0) = 0$ ,  $\psi_2(0) = 0$  for the solvability of systems (2.54) the equality  $b_1(0) = 0$  is sufficient. Under this condition we choose the constant  $c_2$  arbitrarily. Then from (2.54) we have

$$c_1 P_2(\varphi) + \overline{c}_1 P_1(\varphi) = \Delta_2(\varphi_1),$$
 (2.61)

where

$$\Delta_2(\varphi_1) = b_2 - (BF)(\varphi_1) - c_2 Q_2(\varphi_1) - \overline{c}_2 Q_1(\varphi_1).$$

Equation (2.61) has a unique solution in case, when

$$\Lambda_{2}(\varphi_{1}) = |P_{2}(\varphi_{1})|^{2} - |P_{1}(\varphi_{1})|^{2} \neq 0.$$
(2.62)

Under this condition the solution of equation (2.61) is

$$c_{1} = \frac{P_{2}(\varphi_{1})\Delta_{2}(\varphi_{1}) - P_{1}(\varphi_{1})\Delta_{2}(\varphi_{1})}{\left|P_{2}(\varphi_{1})\right|^{2} - \left|P_{1}(\varphi_{1})\right|^{2}},$$
(2.63)

where  $\Delta_2(\varphi_1) = b_2 - (BF)(\varphi_1) - c_2 Q_2(\varphi_1) - \bar{c}_2 Q_1(\varphi_1)$ .

The solvability of equation (2.60) is similar.

In case, when

$$\Lambda_2(\varphi_1) = 0 \tag{2.64}$$

for the solvability of (2.61) the conditions

$$\operatorname{Re}(\overline{\Delta_{2}(\varphi_{1})}(P_{2}(\varphi_{1}) - P_{1}(\varphi_{1}))) = 0, \ \operatorname{Im}(\overline{\Delta_{2}(\varphi_{1})}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))) = 0$$
(2.65)

are necessary and sufficient. When these conditions hold the solution of equation (2.61) is

$$c_{1} = \begin{cases} \frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) + i\alpha(\overline{P_{2}(\varphi_{1})} + P_{1}(\varphi_{1}))}{\operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{2}(\varphi_{1}) - \alpha(\overline{P_{2}(\varphi_{1})} + P_{1}(\varphi_{1}))}{\operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ c_{3}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \end{cases}$$
(2.66)

where  $\alpha$  is any real,  $c_3$  is any complex number.

Thus, the following results holds.

**Theorem 2.11.** 1) When  $\psi_1^2(0) + \psi_2^2(0) \neq 0$ , problem  $D_3$  has a unique solution. This solution is given by formula (1.80), where the numbers  $c_1$ ,  $c_2$  are defined by formula (2.56), when  $\psi_1(0) \neq 0$  and by formula (2.63) when  $\psi_2(0) \neq 0$ .

2) If  $\Lambda_1(\varphi_1) = 0$  and  $\psi_1(0) \neq 0$  or  $\Lambda_2(\varphi_1) = 0$  and  $\psi_1(0) = 0$ ,  $\psi_2(0) \neq 0$ , then for the solvability of problem  $D_3$  the condition (2.58) when  $\psi_1(0) \neq 0$  and (2.65) when  $\psi_1(0) = 0$ ,  $\psi_2(0) \neq 0$  is necessary and sufficient. When the conditions are satisfied problem  $D_3$  has infinitely many solutions. These solutions are given by the formulas (1.80), where  $c_1$  and  $c_2$  are defined by formula (2.59), if  $\Lambda_1(\varphi_1) = 0$ ,  $\psi_1(0) \neq 0$  and by formula (2.66), if  $\Lambda_2(\varphi_1) = 0$ ,  $\psi_1(0) = 0$ ,  $\psi_2(0) \neq 0$ .

3) If  $\psi_1(0) = 0, \psi_2(0) = 0$ , then for the solvability of problem  $D_3$ necessarily holds  $b_1 = 0$ . In this case problem  $D_3$  has infinitely many solutions. These solutions are given by formula (2.61), where one of the numbers  $c_1$ ,  $c_2$  are arbitrary.

Let  $c_2$  be arbitrarily chosen. Then  $c_1$  is given by formula (2.63), if  $\Lambda_2(\varphi_1) \neq 0$  and by formula (2.66), if  $\Lambda_2(\varphi_1) = 0$  and condition (2.65) holds.

**Problem**  $D_4$ . Let  $b(\varphi) = a(\varphi) + c(\varphi)$ ,  $a(\varphi) \neq c(\varphi)$  and  $\lambda \neq 1$ . It is required to find the solution of equation (1.69) from the class (1.3), satisfying the conditions

$$|V(r,\varphi)| = \mathcal{O}(r^{\lambda}), r \to \infty, \qquad (2.67)$$

$$V(r, \varphi_1) = b_1 r^{\lambda},$$
 (2.68)

where  $b_1$  is a given complex number,  $\lambda > 0$  is a given real number.

**Solution of the problem**. For solving problem  $D_4$  formula (1.96) is used. Then (2.67) automatically holds. From the boundary condition (2.68) we get the equation for determining c:

$$cP_2(\varphi_1) + \bar{c}P_1(\varphi_1) = \Delta(\varphi_1),$$
 (2.69)

where  $\Delta(\varphi_1) = b_1 - F_1(\varphi_1)$ .

Equation (2.69) has a unique solution in case, when

$$|P_2(\varphi_1)|^2 \neq |P_1(\varphi_1)|^2.$$
 (2.70)

Under this condition the solution is

$$c = \frac{\Delta(\varphi_1)\overline{P_2(\varphi_1)} - \overline{\Delta_1(\varphi_1)}P_1(\varphi_1)}{|P_2(\varphi_1)|^2 - |P_1(\varphi_1)|^2},$$
(2.71)

Hence, the following result holds.

**Theorem 2.12** When the condition (2.70) is fulfilled problem  $D_4$  has a unique solution. This solution is given by formulas (1.96) and (2.71).

In case, when

$$|P_{2}(\varphi_{1})|^{2} = |P_{1}(\varphi_{1})|^{2}$$
(2.72)

for the solvability of equation (2.69) the conditions

$$\operatorname{Re}(\overline{\Delta(\varphi_{1})}(P_{2}(\varphi_{1}) - P_{1}(\varphi_{1}))) = 0, \operatorname{Im}(\overline{\Delta(\varphi_{1})}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))) = 0.$$
(2.73)

are necessary and sufficient. When these conditions hold, the solution of equation (2.69) is given by the formulas

$$c = \begin{cases} \frac{\operatorname{Re} \Delta(\varphi_{1}) + i\alpha(\overline{P_{2}}(\varphi_{1}) + P_{1}(\varphi_{1}))}{\operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta(\varphi_{1}) - \alpha(\overline{P_{2}}(\varphi_{1}) + P_{1}(\varphi_{1}))}{\operatorname{Im}(-P_{2}}(\varphi_{1}) + P_{1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) \neq 0, \\ c_{1}, & \text{if } \operatorname{Re}(P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \operatorname{Im}(-P_{2}(\varphi_{1}) + P_{1}(\varphi_{1})) = 0, \end{cases}$$
(2.74)

where  $\alpha$  is any real,  $c_1$  is any complex number.

Thus, the following result holds.

**Theorem 2.13.** In case, when (2.72) holds for the solvability of problem  $D_4$  conditions (2.73) are necessary and sufficient. Under these conditions the problem has infinitely many solutions. These solutions are given by formulas (1.96), (2.74).

# 2.4 Dirichlet problem for nonhomogeneous second order partial differential equations in the plane with Fuchs operator in the main part

**Problem**  $D_5$ . Let  $a(\phi) \neq c(\phi)$ . It is required to find the solution of equation (1.97) from the class (1.35), satisfying the conditions

$$V(r, \varphi_1) = t(r),$$
 (2.75)

where  $t(r) = \sum_{k=0}^{\infty} t_k r^{k}$  is convergent in G,  $t_k$  are given complex numbers.

**Solution of the problem**. For solving problem  $D_5$  formula (1.109) is used. Then, from the boundary condition (2.75) follows the equation for  $c_k$ ,

$$c_k P_{k,2}(\varphi_1) + \overline{c}_k P_{k,1}(\varphi_1) = \Delta_k,$$
 (2.76)

where  $\Delta_k = t_k - F_{k,1}(\varphi_1)$ .

Equation (2.76) has a unique solution in case, when

$$\Delta_{\kappa}(\varphi_{1}) = \left| P_{k,2}(\varphi_{1}) \right|^{2} - \left| P_{k,1}(\varphi_{1}) \right|^{2} \neq 0.$$
(2.77)

Under this condition the solution of equation (2.76) are given by the formula

$$c_{k} = \frac{\Delta_{k} P_{k,2}(\varphi_{1}) - \Delta_{k} P_{k,1}(\varphi_{1})}{\left| P_{k,2}(\varphi_{1}) \right|^{2} - \left| P_{k,1}(\varphi_{1}) \right|^{2}}$$
(2.78)

In case, when

$$\Delta_{\kappa}(\varphi_1) = 0 \tag{2.79}$$

for the solvability of equation (2.76) the conditions

$$\operatorname{Re}(\overline{\Delta_{k}}(P_{k,2}(\varphi_{1}) - P_{k,1}(\varphi_{1}))) = 0, \ \operatorname{Im}(\overline{\Delta_{k}}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))) = 0.$$
(2.80)

are necessary and sufficient. When these conditions hold the solution of equation (2.76) is given by

$$c_{k} = \begin{cases} \frac{\operatorname{Re} \Delta_{k} + i\alpha_{k}(\overline{P_{k,2}(\varphi_{1})} + P_{k,1}(\varphi_{1}))}{\operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}, & \text{if } \operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) \neq 0, \\ i\frac{\operatorname{Re} \Delta_{k} - \alpha_{k}(\overline{P_{k,2}(\varphi_{1})} + P_{k,1}(\varphi_{1}))}{\operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1}))}, & \text{if } \operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) \neq 0, \\ c_{k,1}, & \text{if } \operatorname{Re}(P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) = 0, & \operatorname{Im}(-P_{k,2}(\varphi_{1}) + P_{k,1}(\varphi_{1})) = 0, \end{cases}$$
(2.81)

where  $\alpha_k$  is any real,  $c_{k,1}$  is any complex number.

Thus, the following results holds.

**Theorem 2.14.** 1) When  $\Delta_k(\varphi_1) \neq 0$ ,  $0 \leq k$  problem  $D_5$  has a unique solution. This solution is given by the formulas (1.109) and (2.78).

2) If for some index k the equality  $\Delta_k(\varphi_1) = 0$  holds, then for the solvability of problem  $D_5$  conditions (2.80) for this index k are necessary and sufficient. In this case the problem has an infinitely many solutions. These solutions are given by formulas (1.109), where  $c_{\kappa}$  is given by formulas (2.78) if  $\Delta_k(\varphi_1) \neq 0$  and by formulas (2.81) if  $\Delta_k(\varphi_1) = 0$ .