

Model Code

Code for the Capital Fisher Model

See section 4.2 (p. 95) for details. The variables are transformed to replace $D_k v$ by $mvk := -D_k v$ to meet technical limitations of the script language. Some cases where one variables obtains it upper or lower bound are excluded by the `unreachable-values` directive.

```
(quantity-spaces
 (x (0 xmsy Q xmax) "Stock")
 (k (0 kmax) "Capital")
 (I (0 Imax) "Investment")
 (R (0 Rmsy Rmax) "Recruitment")
 (h (0 MSY hmax) "Harvest")
 (mvk (0 inf) "-D_k v")
 (dx (minf 0 inf) "dx")
 (dk (minf 0 inf) "dk")
 (dI (minf 0 inf) "dI"))

(constraints

 ;; derivatives
 ((d//dt x dx))
 ((d//dt k dk))
 ((d//dt I dI))

 ((add dk k I) (0 0 0))
 ((add dx h R) (0 0 0) (0 MSY Rmsy))
 ((add dI mvk I) (0 0 0))

 ;; auxiliary variables
 ((U- x R) (xmsy Rmsy) (0 0) (Q 0))
 (((M + - -) h x k mvk))

 ;; algebraic constraints
 (((M + +) k x h))

 ;; sigma (only second, unambiguous row)
 (((M - +) k I dk)) ; implicit in (add dk k I)
```

```
;; exclusion of marginal edges
((cornot x h) (xmsy MSY))
((cornot x dx) (xmsy 0))
((cornot x dk) (xmsy 0))
((cornot x dI) (xmsy 0))
((cornot h dx) (MSY 0))
((cornot h dk) (MSY 0))
((cornot h dI) (MSY 0)))
```

```
;;; technical directives
```

```
(unreachable-values
 (x xmax) (k kmax) (I 0 Imax) (R Rmax) (h hmax) (mvk 0))
```

Code of the Negotiation Model with Capital

The basic model with unconstrained recommendations r and restricted quantity space (see section 4.3.2, p. 109).

```
(quantity-spaces
 (x (xmin xv xmsy) "Stock")
 (k (0 kmax)       "Capital")
 (h (hmin MSY hmax) "Harvest")
 (r (0 hmin rmax)  "Catch Recommendation")
 (dx (minf 0 inf)  "dx")
 (dk (minf 0 inf)  "dk")
 (dh (minf 0 inf)  "dh"))

(constraints
 ((d//dt x dx))
 ((d//dt k dk))
 ((d//dt h dh))

; basic constraints
(((M + -) x h dx) (xv hmin 0) (xmsy MSY 0))
(((M - +) k h dk))
(((M + + +) x k r h))

; exclude k=0 and h>0
(((NQ -0 +0) k h) (0 hmin))

; h > r
(((NQ - +) h r) (hmin hmin))

; exclusion of marginal edges

((cornot x h) (xv hmin))
((cornot x h) (xv MSY))
((cornot x h) (xmin hmin))
((cornot x h) (xmin MSY))
((cornot x h) (xmsy hmin))
((cornot x h) (xmsy MSY))

((cornot x r) (xv hmin))
((cornot x r) (xmin hmin))
((cornot x r) (xmsy hmin))

((cornot x dx) (xv 0))
((cornot x dx) (xmin 0))
((cornot x dx) (xmsy 0))
((cornot x dk) (xv 0))
((cornot x dk) (xmin 0))
((cornot x dk) (xmsy 0))
((cornot x dh) (xv 0))
((cornot x dh) (xmin 0))
```

```
((cornot x dh) (xmsy 0))

((cornot h dx) (hmin 0))
((cornot h dx) (MSY 0))
((cornot h dk) (hmin 0))
((cornot h dk) (MSY 0))
((cornot h dh) (hmin 0))
((cornot h dh) (MSY 0))

((cornot r dx) (hmin 0))
((cornot r dk) (hmin 0))
((cornot r dh) (hmin 0))

((cornot dx dk) (0 0))
((cornot dx dh) (0 0))
((cornot dk dh) (0 0))

; technical directives

(unreachable-values
 (k kmax) (h hmax) (r 0 rmax))

(weak-cycles)

(with-envisionment)

; initial state of simulation

(make-initial-state
 (x ((xv xmsy) dec))
 (k ((0 kmax) nil))
 (r ((hmin rmax) nil))
 (h ((hmin MSY) nil)))
```

Negotiation Model with Capital and a further restricted qualitative state space. The code contains different constraints for r :

```
(quantity-spaces
 (x (xv xmsy)      "Stock")
 (k (0 kmax)       "Capital")
 (r (0 hmin rmax)  "Catch Recommendation")
 (h (hmin MSY hmax) "Harvest")
 (dx (minf 0 inf)  "dx")
 (dk (minf 0 inf)  "dk")
 (dh (minf 0 inf)  "dh")
 (dr (minf 0 inf)  "dr"))

(constraints
 ((d//dt x dx))
 ((d//dt k dk))
 ((d//dt h dh))
 ((d//dt r dr))

; basic constraints
(((M + -) x h dx) (xv hmin 0) (xmsy MSY 0))
(((M - +) k h dk))
(((M + + +) x k r h))

; conservative control
; ((M- h dr) (hmin 0))
; qualitative control
(((M - + -) x dx dh r) (xmsy 0 0 hmin))
(((M - + -) x k h dh))

; exclude k=0 and h>0
(((NQ -0 +0) k h) (0 hmin))

; r < h
(((NQ - +) h r) (hmin hmin))

;; exclusion of marginal edges

((cornot x h) (xv hmin))
((cornot x h) (xv MSY))
((cornot x h) (xmsy hmin))
((cornot x h) (xmsy MSY))

((cornot x r) (xv hmin))
((cornot x r) (xmsy hmin))

((cornot x dx) (xv 0))
((cornot x dx) (xmsy 0))
((cornot x dk) (xv 0))
((cornot x dk) (xmsy 0))
((cornot x dh) (xv 0))
```

```
((cornot x dh) (xmsy 0))
((cornot x dr) (xv 0))
((cornot x dr) (xmsy 0))
```

```
((cornot h dx) (hmin 0))
((cornot h dx) (MSY 0))
((cornot h dk) (hmin 0))
((cornot h dk) (MSY 0))
((cornot h dh) (hmin 0))
((cornot h dh) (MSY 0))
((cornot h dr) (hmin 0))
((cornot h dr) (MSY 0))
```

```
((cornot r dx) (hmin 0))
((cornot r dk) (hmin 0))
((cornot r dh) (hmin 0))
```

```
((cornot dx dk) (0 0))
((cornot dx dh) (0 0))
((cornot dk dh) (0 0))
((cornot dx dr) (0 0))
((cornot dk dr) (0 0))
((cornot dh dr) (0 0))
```

```
;;; technical directives
```

```
(unreachable-values
 (k kmax) (h hmax) (r 0 rmax))
```

```
(weak-cycles)
```

```
(with-envisionment)
```

```
;;; initial state of simulation
```

```
(make-initial-state
 (x ((xv xmsy) dec))
 (k ((0 kmax) nil))
 (r ((hmin rmax) nil))
 (h ((hmin MSY) nil)))
```

Model Code for Lake Management

The basic model with unconstrained phosphorus input L (see section 4.4, p. 116).

```
(quantity-spaces
  (P (0 11 12 eu) "lake phosphorus")
  (M (0 inf) "sediment phosphorus")
  (L (0 inf) "intake")
  (dP (minf 0 inf) "dP")
  (dM (minf 0 inf) "dM")
  (dL (minf 0 inf) "dL")
  (phi (0 1) "regime")
  (r (0 inf) "recycling"))
```

```
(constraints
  ((d//dt P dP))
  ((d//dt M dM))
  ((d//dt L dL))

  (((M + - ) P M dM))
  (((M - + +) P r L dP))
  ((mult M phi r) (0 0 0))
  ((S+ P phi) (11 0) (12 1))

  ((cornot dP dM) (0 0))
  ((cornot dP dL) (0 0))
  ((cornot dL dM) (0 0)))
```

```
(unreachable-values
  (M 0) (L 0) (P 0))
```

```
(with-envisionment)
```

```
(make-initial-state
  (P ((0 11) nil))
  (M ((0 inf) nil))
  (L ((0 inf) nil)))
```

Version with qualitative lake management. The quantity space is restricted to $P \geq \lambda_*$.

```
(quantity-spaces
  (P (l1 l* l2 eu) "lake phosphorus")
  (M (0 inf) "sediment phosphorus")
  (L (0 inf) "intake")
  (dP (minf 0 inf) "dP")
  (dM (minf 0 inf) "dM")
  (dL (minf 0 inf) "dL")
  (phi (0 phil* 1) "regime")
  (r (0 inf) "recycling"))

(constraints
  ((d//dt P dP))
  ((d//dt M dM))
  ((d//dt L dL))

  ((M + - ) P M dM))
  ((M - + +) P r L dP))
  ((mult M phi r) (0 0 0))
  ((S+ P phi) (l1 0) (l2 1) (l* phil*))
  ((M - + +) P M L dP))

; control
  ((M + - -) P M L dL))

  ((cornot dP dM) (0 0))
  ((cornot dP dL) (0 0))
  ((cornot dL dM) (0 0)))

(unreachable-values
  (M 0) (L 0) (P l1))

(with-envisionment)

(make-initial-state
  (P ((l* l2) nil))
  (M ((0 inf) nil))
  (L ((0 inf) nil)))
```
