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# Notation and Definitions

Here I list often used abbreviations and notations for quick reference. The notation in chapter 3 complies to Steffen Lauritzen's book [72], the statistical standard reference on graphical models.

## Chapter 1

DNA.....	Deoxyribonucleic acid
RNA.....	Ribonucleic acid
mRNA.....	messenger RNA
RNAi.....	RNA interference

## Chapter 2

$V$ .....	set of graph vertices representing network components
$p$ .....	number of pathway components, $p =  V $ .
$T = (V, \mathcal{E})$ .....	network topology on vertices $V$ and edge set $\mathcal{E}$
$D$ .....	special case: $T$ is a directed acyclic graph
$X, x$ .....	a random variable and its realization
$\mathbf{X}, \mathbf{x}$ .....	a set or vector of random variables and its realization
$M$ .....	data matrix $M = \{\mathbf{x}^1, \dots, \mathbf{x}^N\}$
$N$ .....	sample size
$P(X = x) \equiv p(x)$ .....	if no confusion can arise
$X \perp Y$ .....	$X$ and $Y$ are independent random variables
$X \perp Y \mid Z$ .....	$X$ and $Y$ are independent given $Z$
$\Sigma, \hat{\Sigma}$ .....	covariance matrix and its estimator
$K$ .....	precision matrix, inverse covariance matrix, $K = \Sigma^{-1}$
$\theta_{v pa(v)}$ .....	the parameters of random variable $X_v$ given the values of its parents $\mathbf{X}_{pa(v)}$ in the Bayesian network DAG
$\alpha_{i_\delta \mathbf{i}_{pa(\delta)}}$ .....	Dirichlet parameters for a discrete node $\delta \in V$ with parent state $\mathbf{i}_{pa(\delta)}$ in a Bayesian network.
DAG .....	directed acyclic graph
GGM .....	Gaussian graphical model
DBN .....	dynamic Bayesian network
LPD .....	local probability distribution

### Chapter 3

$do(X_v = x'_v)$	do-operator: $X_v$ is fixed to state $x'_v$
$d(x)$	Dirac-function, point mass at $x = 0$
$\Delta$	the set of discrete vertices
$\Gamma$	the set of Gaussian vertices
$\mathbf{X} = (\mathbf{I}, \mathbf{Y})$	the set of variables splits into discrete ones ( $\mathbf{I}$ ) and continuous ones ( $\mathbf{Y}$ ).
$I_\delta, i_\delta$	a discrete random variable ( $\delta \in \Delta$ ) and its realization
$Y_\gamma, y_\gamma$	a Gaussian random variable ( $\gamma \in \Gamma$ ) and its realization
$\mathcal{I}_\delta, \mathcal{I}_{pa(\delta)}$	the state space of $I_\delta$ and its parents $\mathbf{I}_{pa(\delta)}$
$\mathcal{P}(\theta, w, t)$	pushing operator applied to parameters $\theta$ with strength $w$ towards target state $t$
$\theta_{\delta \mathbf{i}_{pa(\delta)}}$	parameters of discrete variable $I_\delta$
$\theta_{\gamma \mathbf{i}_{pa(\gamma)}}$	parameters of Gaussian variable $Y_\gamma$ depending on the values $\mathbf{i}_{pa(\gamma)}$ of discrete parents

### Chapter 4

$V = \mathbf{E} \cup \mathbf{S}$	vertices correspond to signaling genes (S-genes) and reporter genes (E-genes)
$E_i$	reporter genes ( $i = 1, \dots, m$ )
$S_j$	signaling genes ( $j = 1, \dots, p$ )
$E_{ik}, e_{ik}$	binomial random variable corresponding to the state of $E_i$ in experiment $k$ and its realization
$C_{ik}$	continuous expression states
$T$	pathway topology on S-genes
$T'$	extended topoloy including S-genes and E-genes
$\Phi$	silencing scheme
$\alpha$	probability to observe a false positive effect
$\beta$	probability to observe a false negative effect
$\theta_i = j$	position parameter: $S_j$ is the parent of $E_i$ in $T'$
$\eta_i$	probability to observe an effect at $E_i$
$\eta_{is}$	probability to observe an effect at $E_i$ given parent state $s$
$M_i^s$	data of $E_i$ when parent was in state $s$
$n_{ise}$	number of observations $e_{ik} = e$ when parent state is $s$